

Lecture Content

Digital VLSI Design

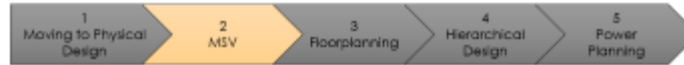
Lecture 6: Moving to the Physical Domain

Semester A, 2018-19
Lecturer: Dr. Adam Teman

December 23, 2018



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A bit about Multiple Voltage Domains

Often referred to as "Low Power Design" Methodologies

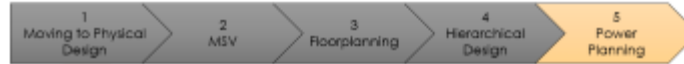


Floorplanning



A bit about Hierarchical Design

Or how do you deal with a really big chip



Power Planning



Digital VLSI Design

Lecture 6: Moving to the Physical Domain

Semester A, 2018-19

Lecturer: Dr. Adam Teman

December 24, 2018



Emerging Nanoscaled
Integrated Circuits and Systems Labs



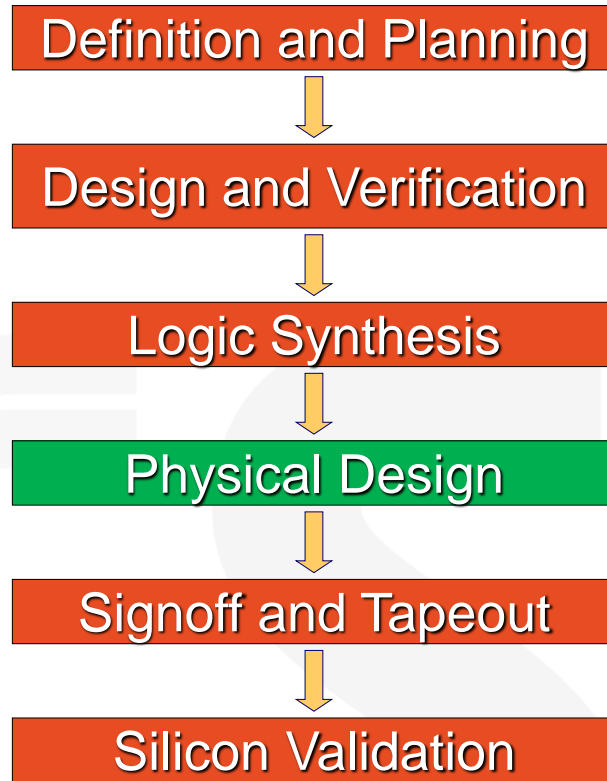
Bar-Ilan University
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So, what's next?

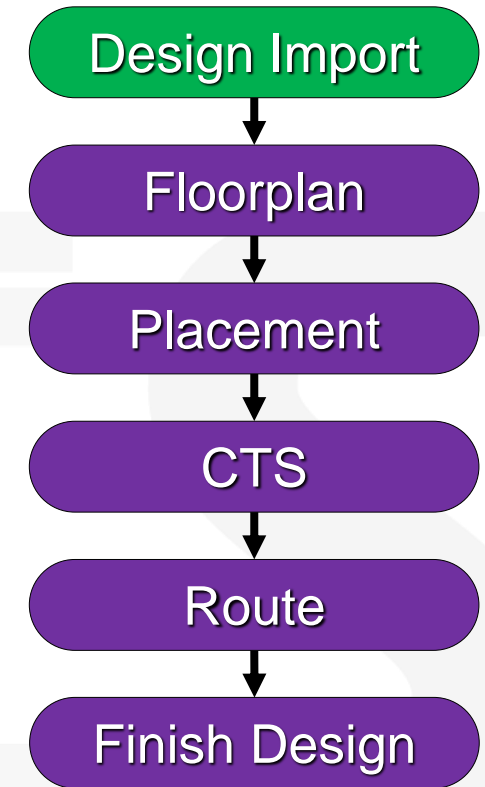
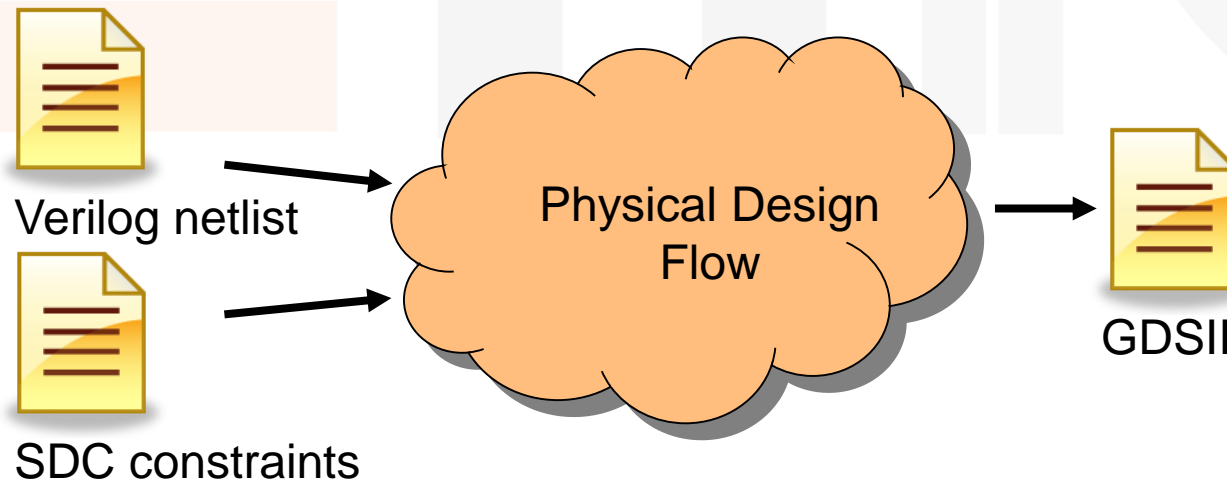
- We've basically finished the *Front-End* of the design process and we will now start the *Back-End*:

- To start, we will move between tools with a *logical* approach to ones with a *physical* approach to design implementation.
- Then, we will make a physical foundation for our design by drawing up a *floorplan*.
 - This will include making decisions where “big” or “important” pieces will sit, such as IPs, I/Os, Power grids, special routes, etc.
- After that, we can *place* our gates taking into account *congestion* and *timing*.
- With our flip-flops in place, we can go about designing a *clock-tree*.
- And finally, we can *route* all our nets, according to *DRCs*, *timing*, *noise*, etc.
- Before *tapeout*, we will clean things up, verify, etc.



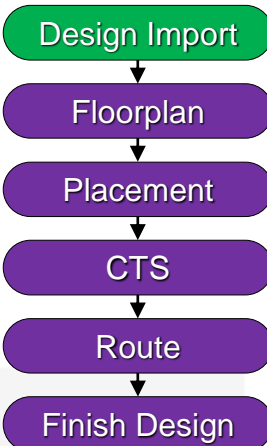
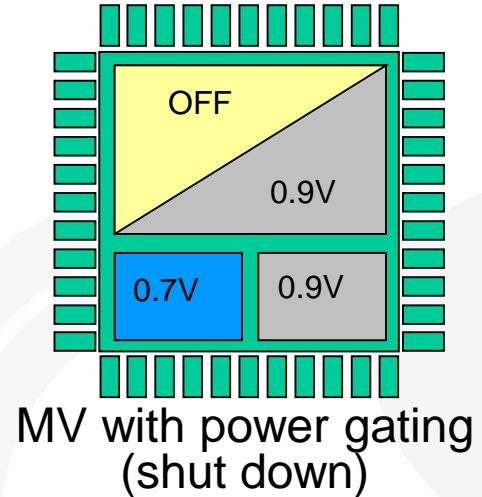
Moving from Logical to Physical

- Define design (.v)
- Define design constraints/targets (.sdc)
- Define operating conditions/modes (MMMC)
- Define technology and libraries (.lef)
- Define physical properties (Floorplan)



Moving from Logical to Physical

- **During synthesis, our world view was a bit idealistic.**
 - We didn't care about **power supplies**.
 - We didn't care about **physical connections/entities**.
 - We didn't care about **clock non-idealities**.
- **Therefore, in order to start physical implementation:**
 - Define “global nets” and how they connect to physical instances.
 - Provide technology rules and cell abstracts (**.lef** files)
 - Provide physical cells, unnecessary for logical functionality:
 - **Tie cells**, **P/G Pads**, **DeCaps**, **Filler cells**, etc.
 - Define **hold** constraints and all operating modes and conditions (**MMMC**)
 - Hold was “easy to meet” with an **ideal clock**, so we didn't really check it...
 - Set up “low power” definitions, such as voltage domains, power gates, body taps, etc.



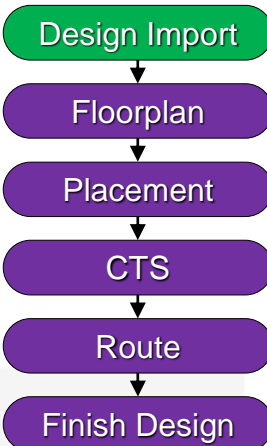
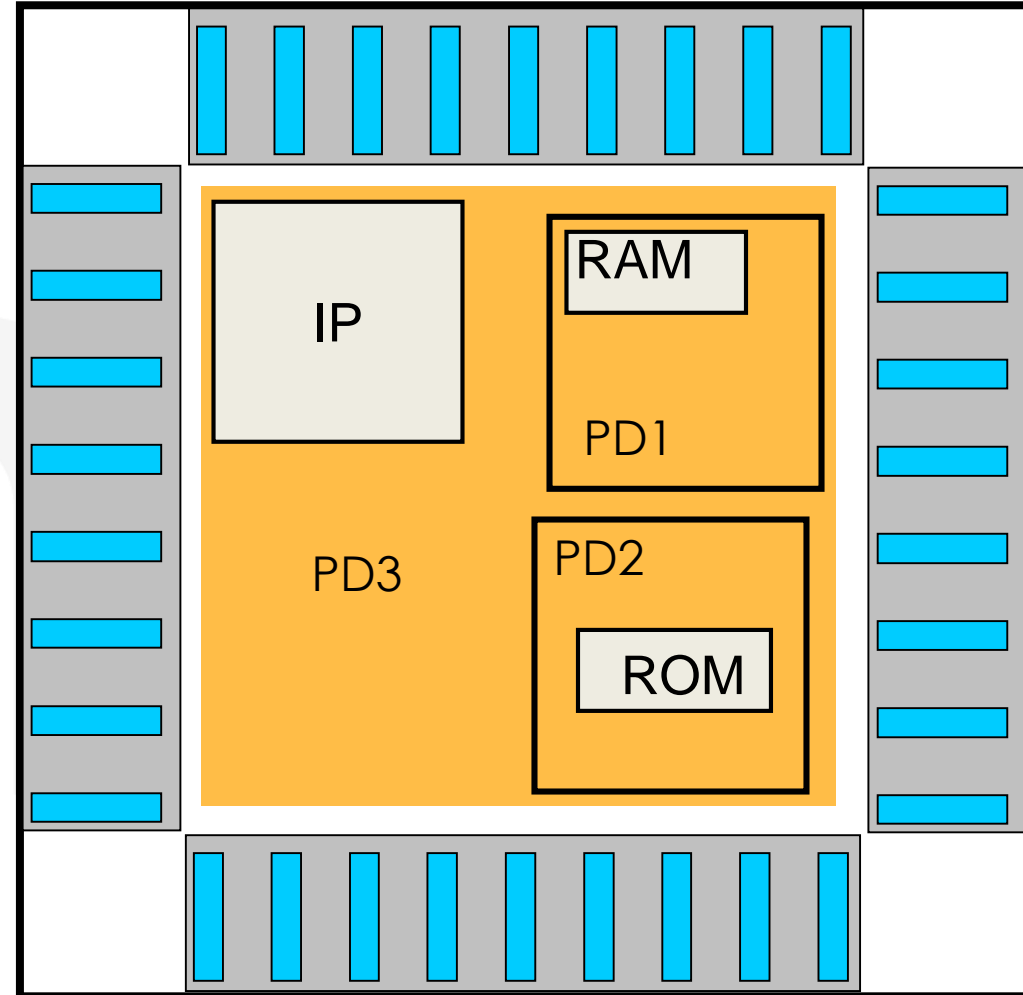


A bit about Multiple Voltage Domains

Often referred to as “Low Power Design” Methodologies

Multiple Domain Design

- **Define power domains**
 - Create power domain names
 - List of cells connected to **VDD1**, **VDD2**, **GND1**,...
 - Draw the power domains
- **Place macros**
 - Take into account:
 - Routing congestion
 - Orientation
 - *Manual* usually better than *Auto*
- **Place switches**
 - For the power down domains



Multiple Domain Design – Level Shifters

Design Import

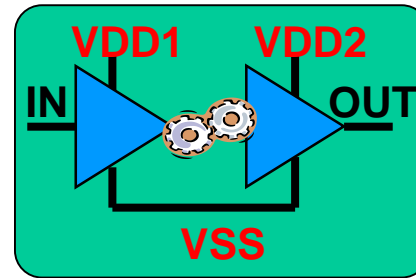
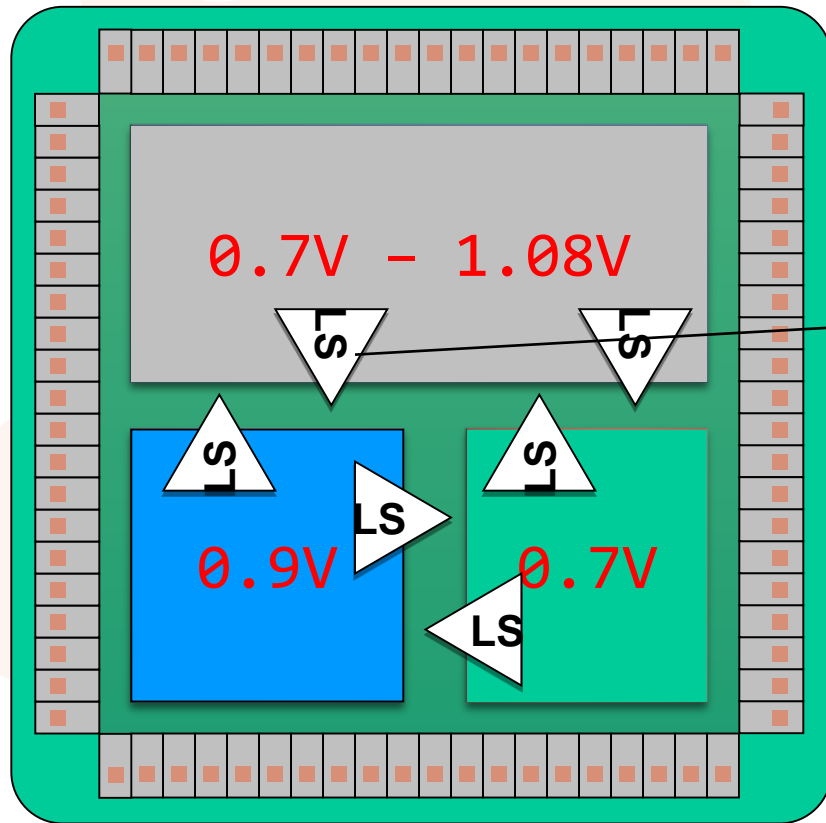
Floorplan

Placement

CTS

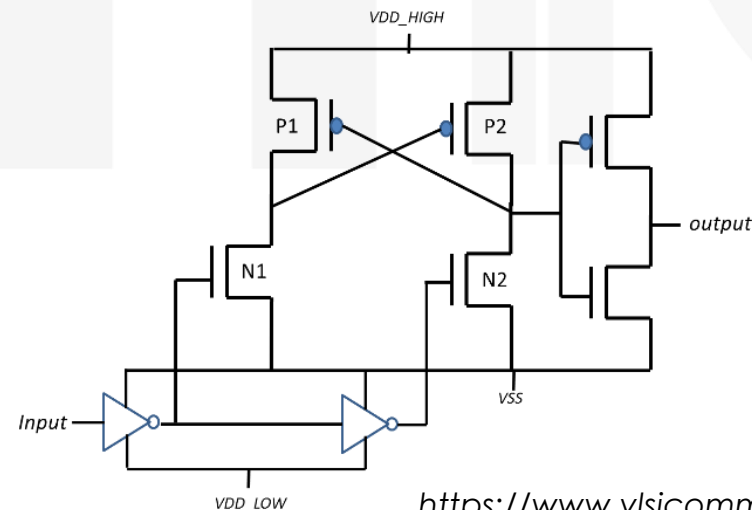
Route

Finish Design

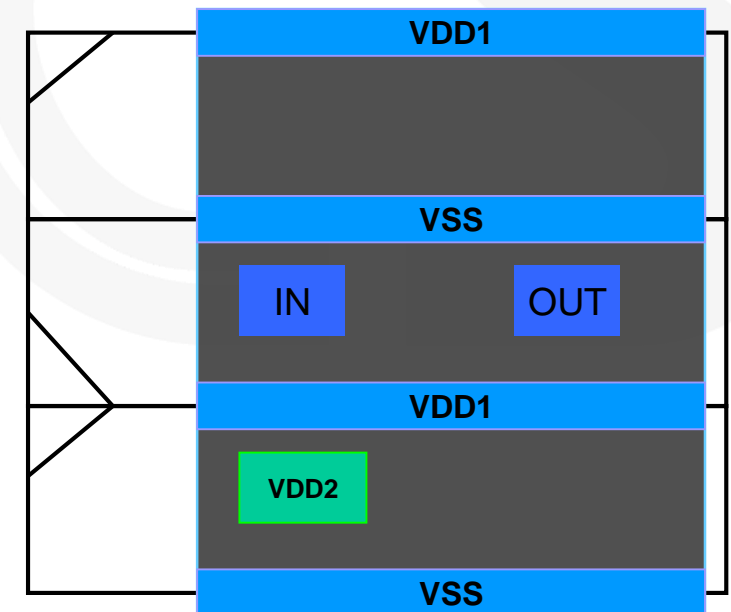


logic model

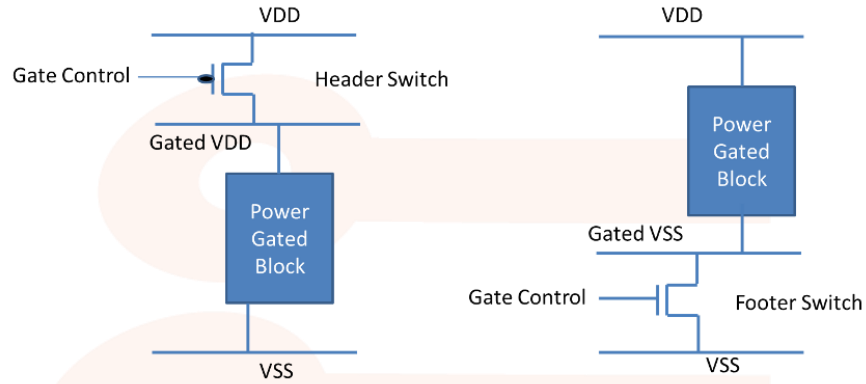
Dual High-to-Low and Low-to-High level shifter



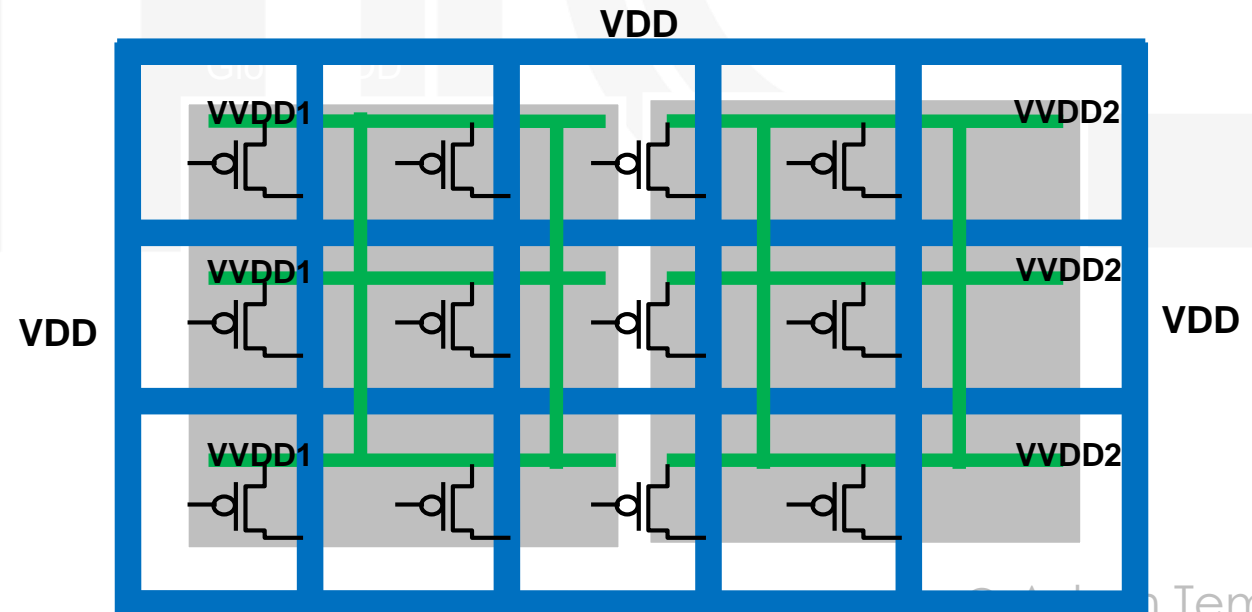
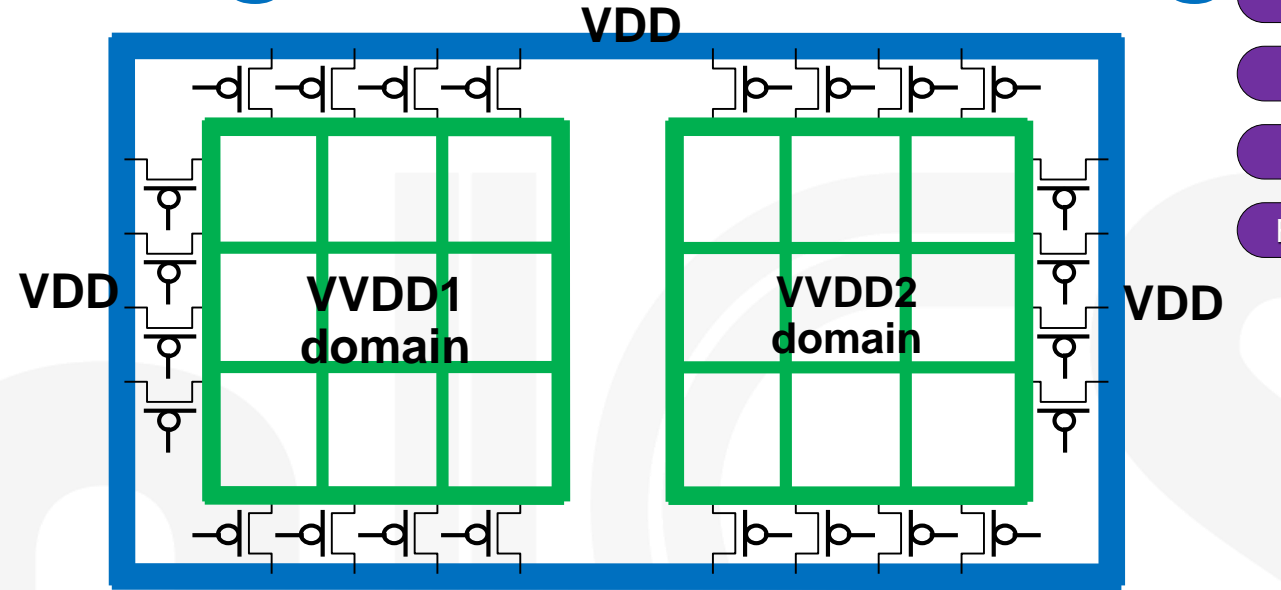
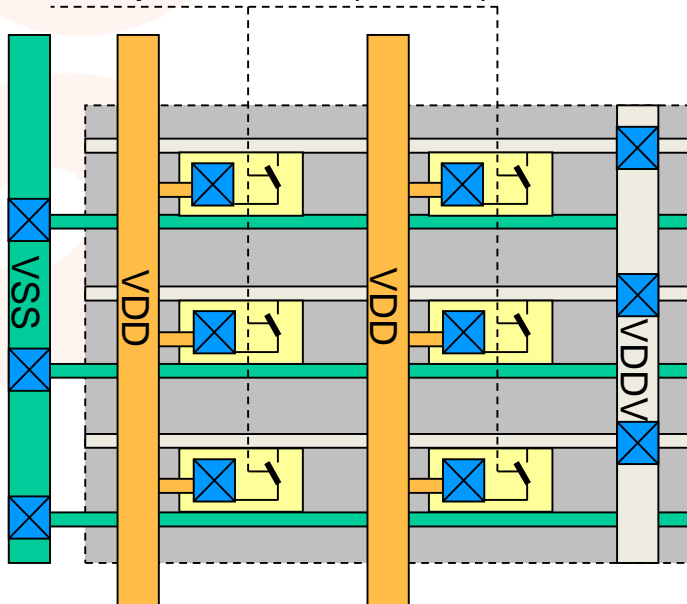
Double row Shifter Floorplan



Multiple Domain Design – Power Gating



sleep_control (on/off)



Design Import

Floorplan

Placement

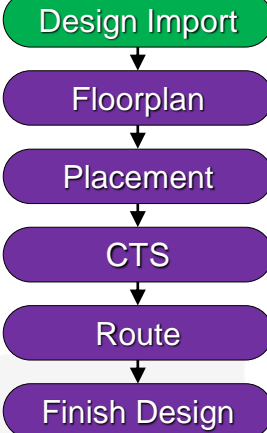
CTS

Route

Finish Design

How do we define this?

- Well, we probably will leave that to an advanced course or your MSc research...
- But, in general, there is a command format for this.
 - Well, actually **two**.
 - Cadence calls theirs **CPF** (**C**ommon **P**ower **F**ormat), and it's surprisingly (...confusingly) similar to **MMMC**.
 - Synopsys calls theirs **UPF** (**U**nified **P**ower **F**ormat), and it's surprisingly similar to **SDC**.
 - I guess neither is very *common* or *unified*...
- Luckily for you, we will not talk any more about this right now 😊.
- Instead, we'll start with the basics of **Floorplanning**.

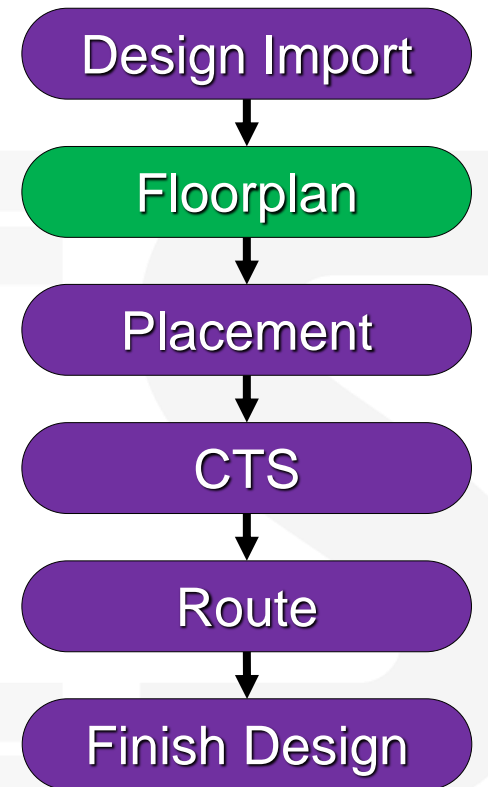




Floorplanning

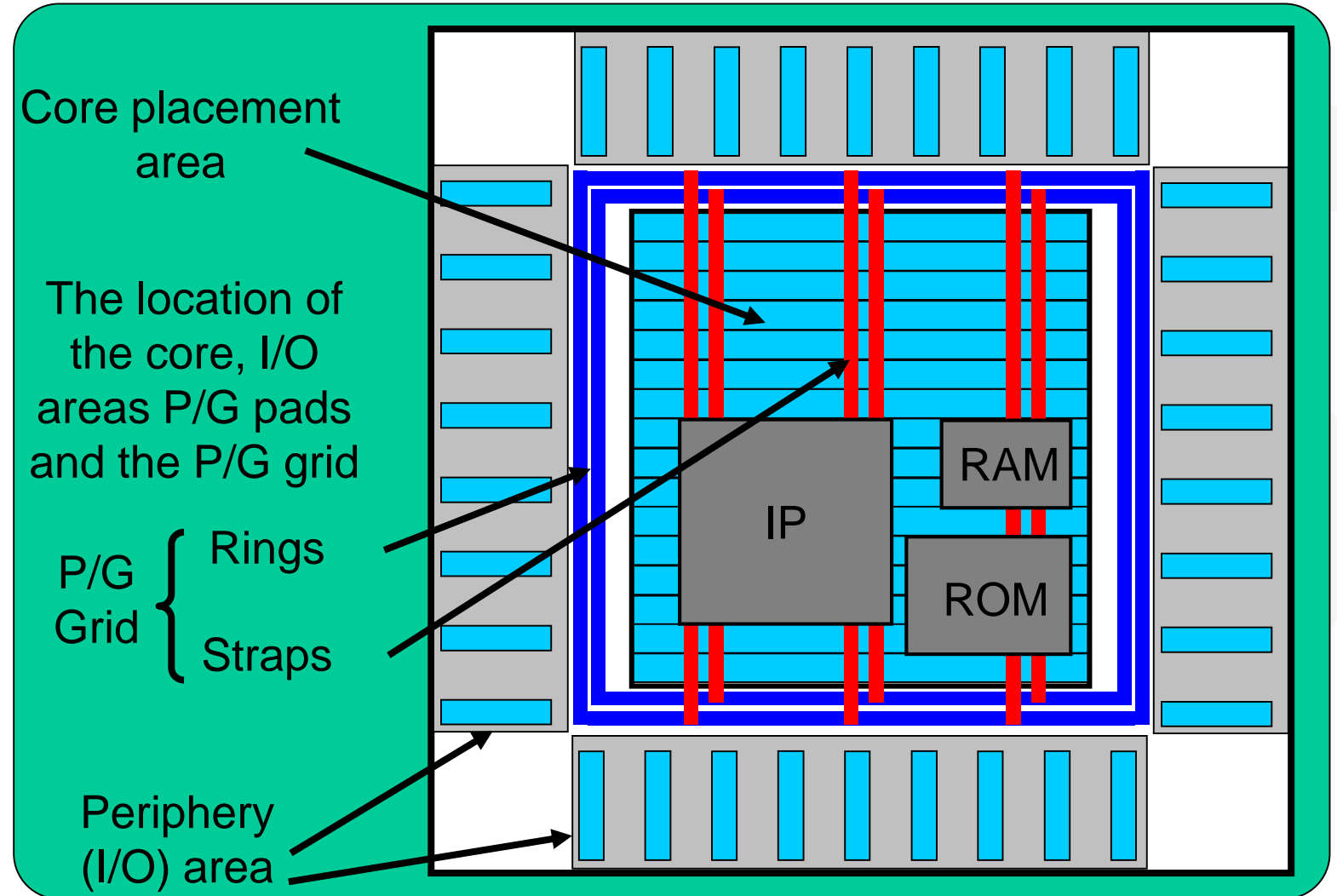
Floorplanning Goals and Objectives

- **Floorplanning** is a mapping between the **logical description** (the **netlist**) and the **physical description** (the **floorplan**).
- **Goals of floorplanning:**
 - Arrange the **blocks** on a chip.
 - Decide the location of the **I/O pads**.
 - Decide the location and number of the **power pads**.
 - Decide the type of **power distribution**.
 - Decide the location and type of **clock distribution**.
- **Objectives of floorplanning are:**
 - Minimize the **chip area**
 - Minimize **delay**
 - Minimize **routing congestion**



Fullchip Design Overview

- Chip size
- Number of Gates
- Number of Metal layers
- Interface to the outside
- Hard IPs/Macros
- Power Delivery
- Multiple Voltages
- Clocking Scheme
- Flat or Hierarchical?



Floorplanning Inputs and Outputs

• Inputs

- Design netlist (required)
- Area requirements (required)
- Power requirements (required)
- Timing constraints (required)
- Physical partitioning information (required)
- Die size vs. performance vs. schedule trade-off (required)
- I/O placement (optional)
- Macro placement information (optional)

• Outputs

- Die/block area
- I/Os placed
- Macros placed
- Power grid designed
- Power pre-routing
- Standard cell placement areas
- **Design ready for standard cell placement**

Design Import

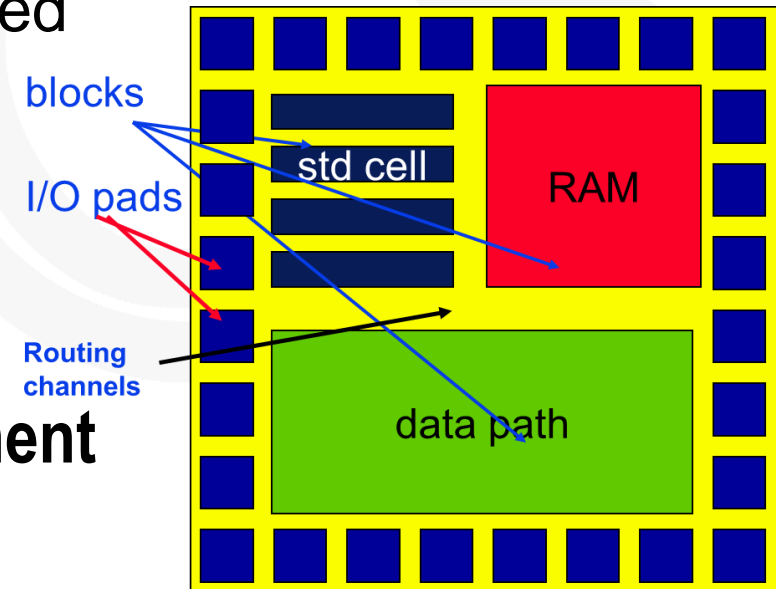
Floorplan

Placement

CTS

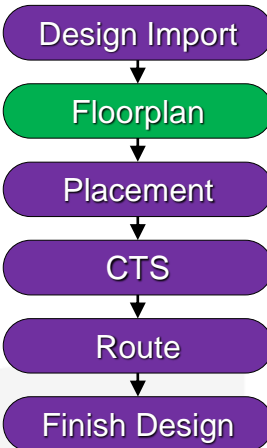
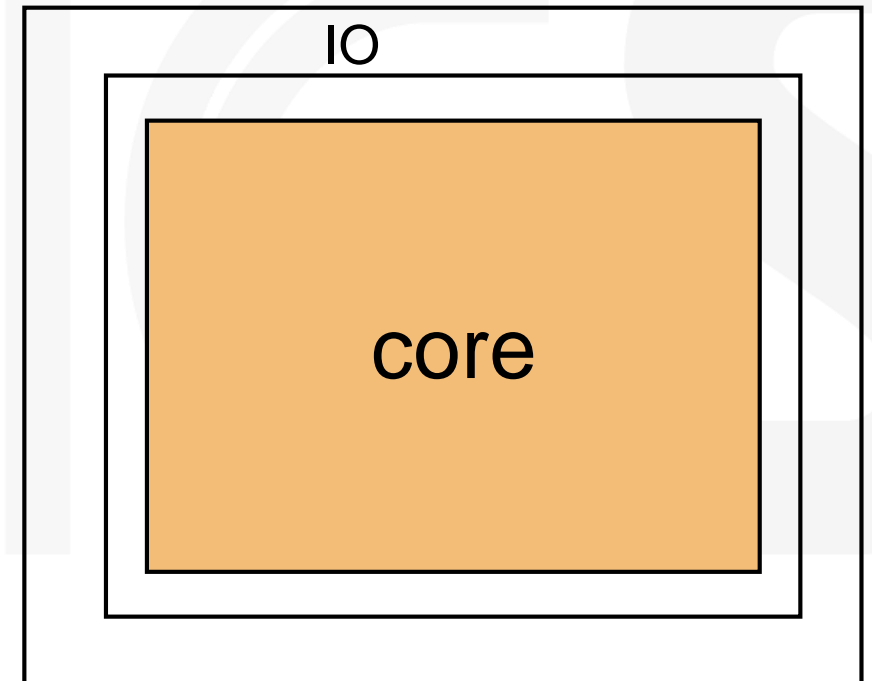
Route

Finish Design



IO Ring

- The pinout is often decided by front-end designers, with input from physical design and packaging engineers.
 - I/Os do not tend to scale with Moore's Law and therefore, they are very expensive (in terms of area).
 - I/Os are not only needed for connecting signals to the outside world, but also to provide power to the chip.
 - Therefore, I/O planning is a critical and very central stage in Floorplanning the chip.
- Let's leave it at that for a bit, and revisit the I/Os a little later...



How do we choose our chip size?

Design Import

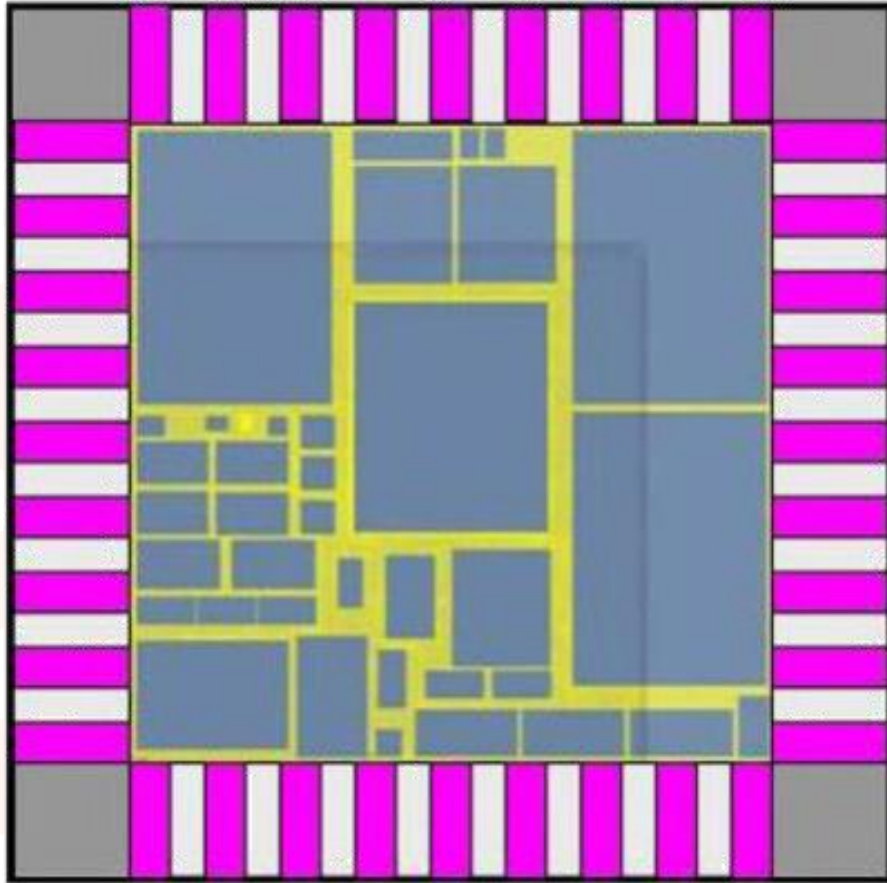
Floorplan

Placement

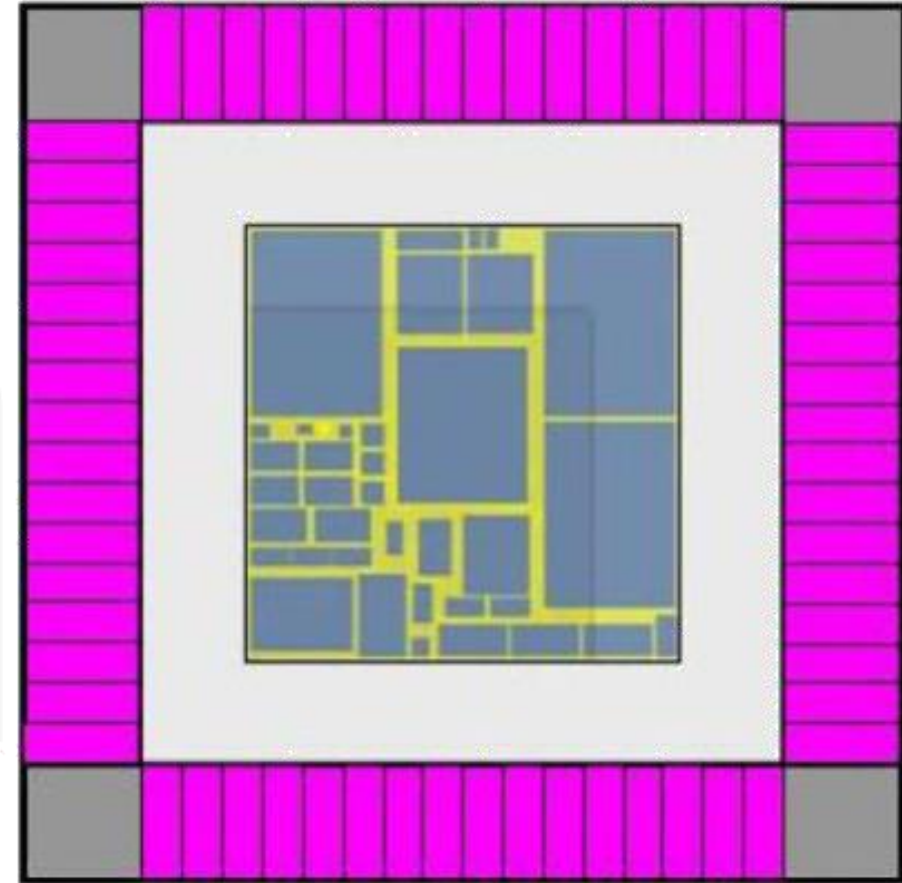
CTS

Route

Finish Design



“Core Limited”



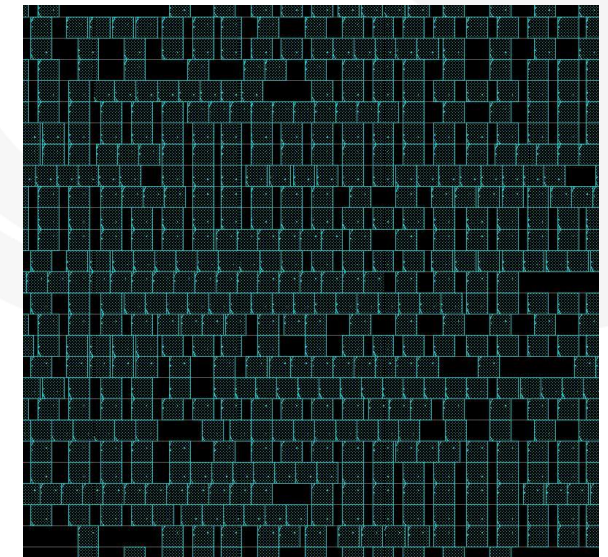
“Pad Limited”

Utilization

- **Utilization** refers to the percentage of core area that is taken up by standard cells.
 - A typical starting utilization might be 70%
 - This can vary a lot depending on the design
- **High utilization can make it difficult to close a design**
 - Routing congestion,
 - Negative impact during optimization legalization stages.
- **Local congestion**
 - Can occur with pin-dense cells like multiplexers, so utilization is not completely sufficient for determining die size.
 - Run a quick trial route to check for routing congestion
 - Refine the synthesis or increase routing resources



Low standard-cell utilization

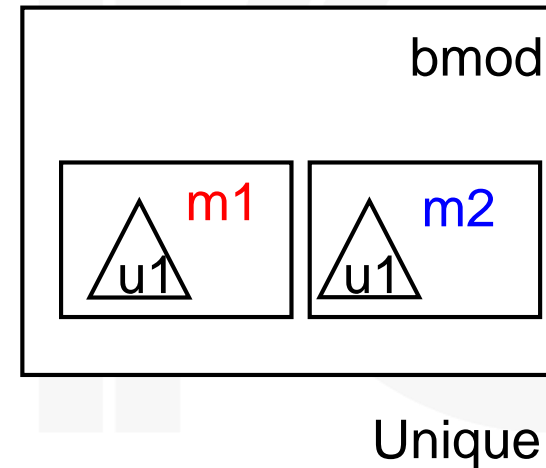
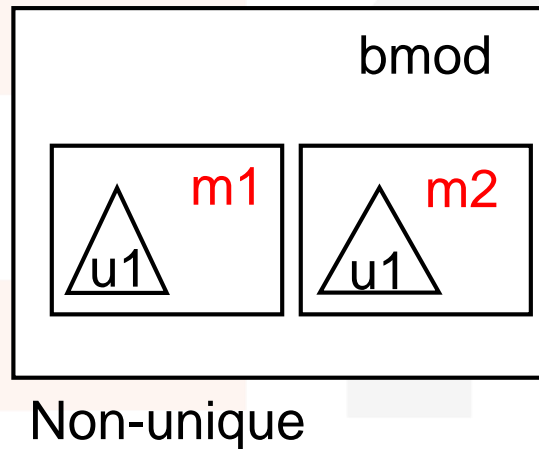


High standard-cell utilization

Uniquifying the Netlist

- When moving to the physical domain, the netlist must be **unique**
 - A **unique netlist**, means that each sub-module is only referenced once.
 - In the example, the non-unique netlist cannot optimize instance m1/u1 without changing instance m2/u1

```
module amod ();  
  BUFFD1 u1 ();  
endmodule  
  
module bmod ();  
  amod m1 ;  
  amod m2 ;  
endmodule
```

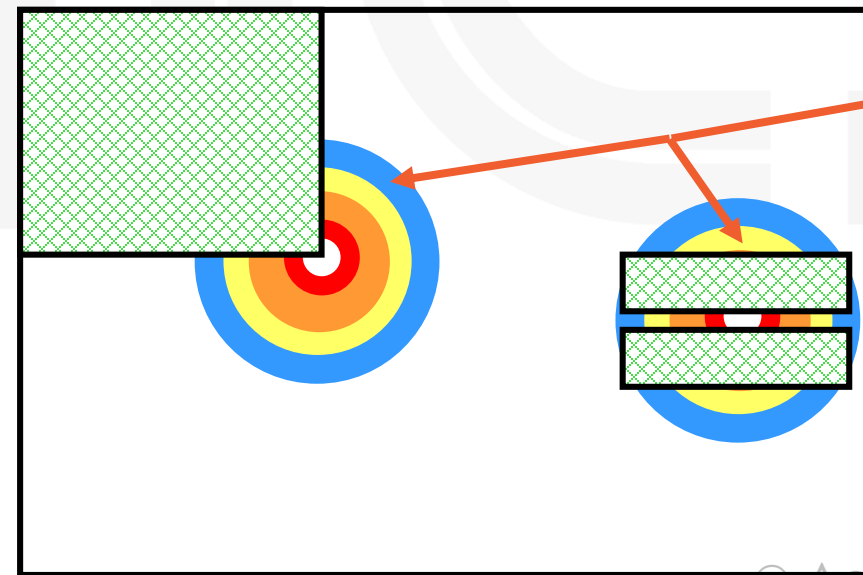
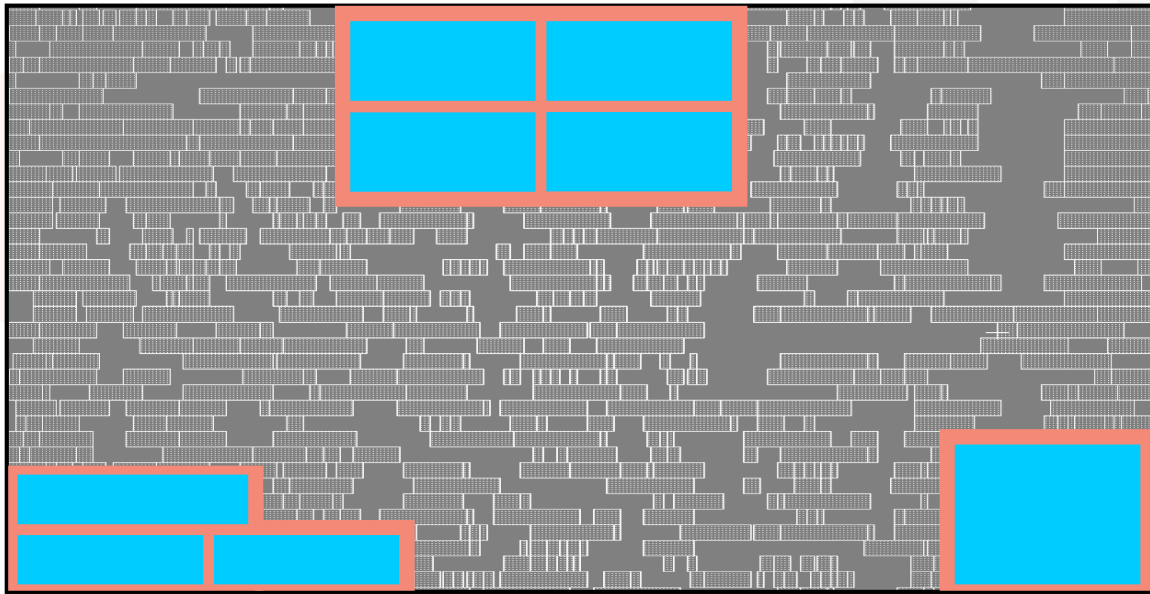
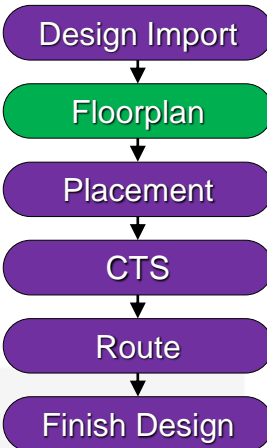


```
module amod1 ();  
  BUFFD1 u1 ();  
endmodule  
  
module amod2 ();  
  BUFFD1 u1 ();  
endmodule  
  
module bmod ();  
  amod1 m1 ;  
  amod2 m2 ;  
endmodule
```

- A synthesized netlist must be **uniquified** before placement can begin. This can be done either by the synthesizer or during design import.

Hard Macro Placement

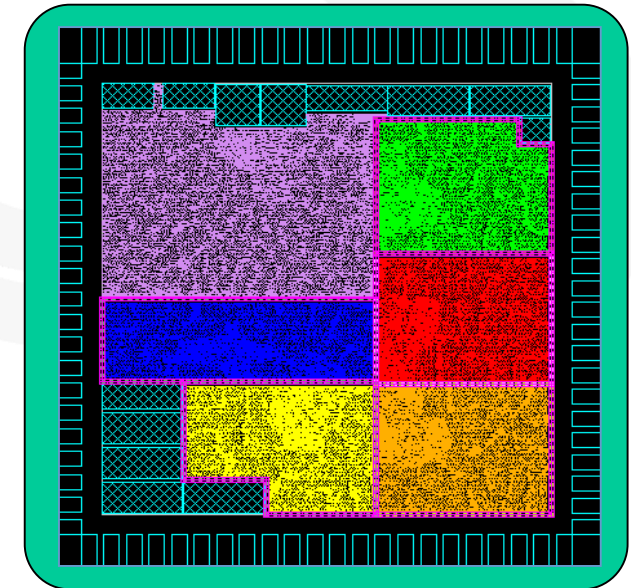
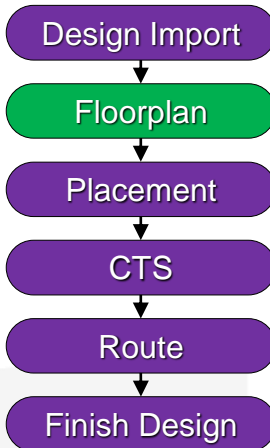
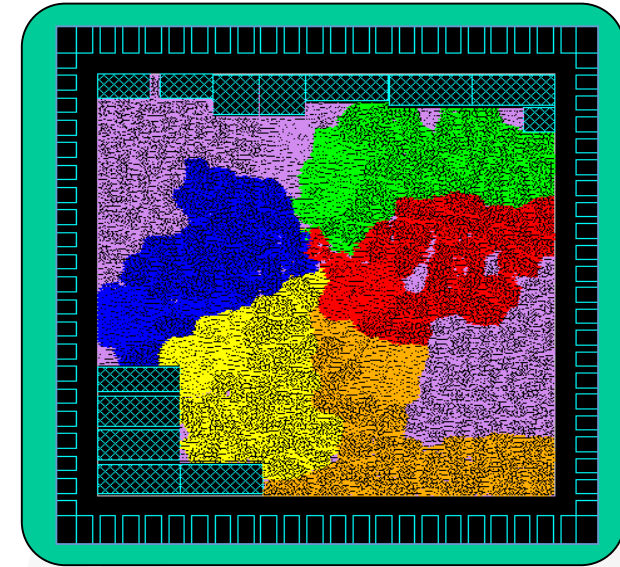
- When placing large macros we must consider impacts on routing, timing and power. Usually **push them to the sides** of the floorplan.
 - Placement algorithms generally perform better with a **single large rectangular placement area**.
 - For wire-bond place power hungry macros **away from the chip center**.
- After placing hard macros, mark them as **FIXED**.



Possible
routing
congestion
hotspots

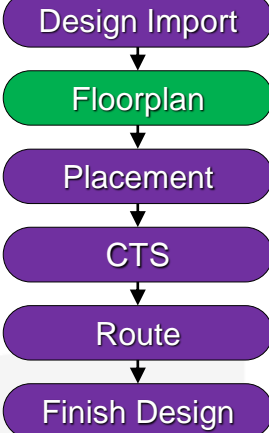
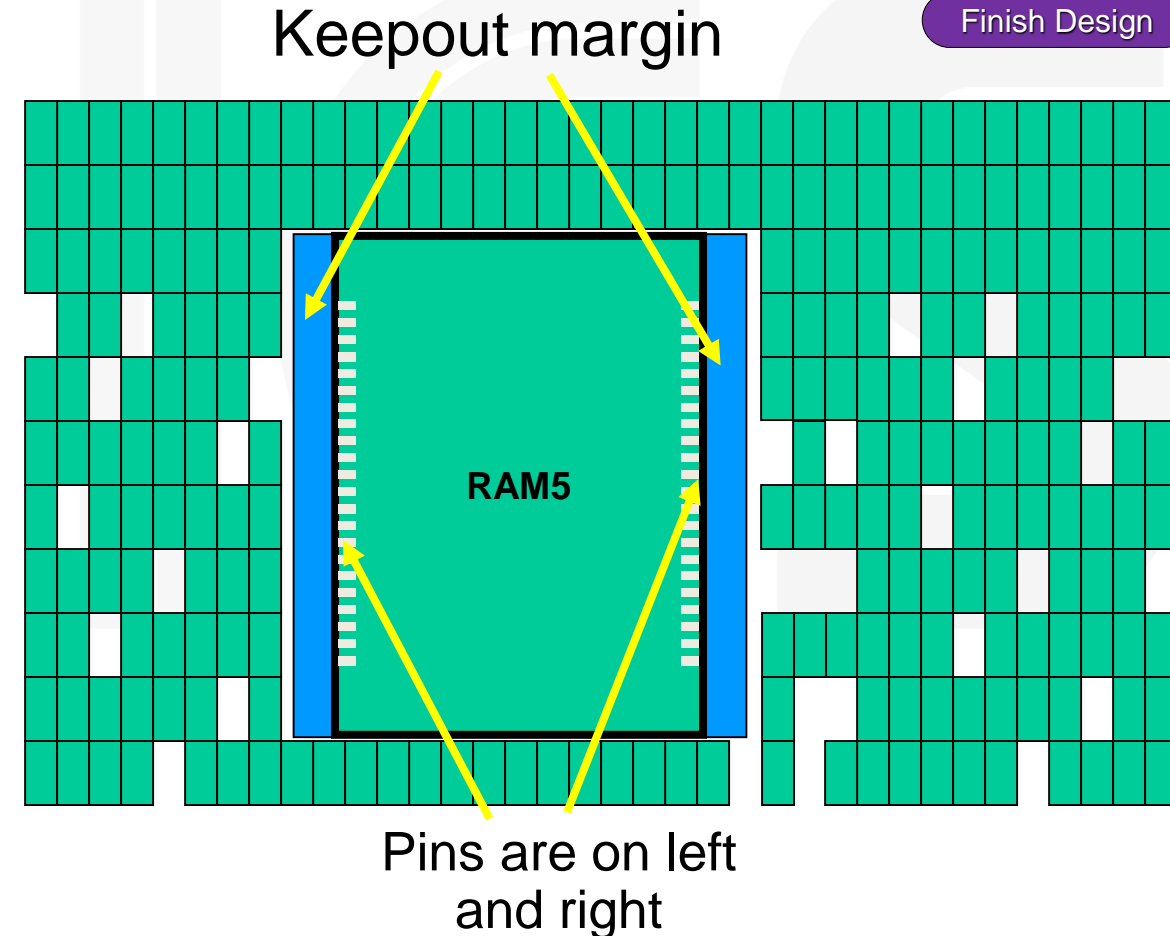
Placement Regions

- Sometimes, we want to “help” the tool put certain logic in certain regions or cluster them together.
- Place and Route tools define several types of placement regions:
 - **Soft guide** – *try* to cluster these cells together without a defined area.
 - **Guide** – *try* to place the cells in the defined area.
 - **Region** – must place the cells in the defined area, but other cells may also be placed there.
 - **Fence** – must place the cells in the defined area and keep out all other cells.



Placement Blockages and Halos

- Placement blockage **halos** are areas that the tools *should not* place any cells.
- These, too, have several types:
 - **Hard Blockage** – no cells can be placed inside.
 - **Soft Blockage** – cannot be used during placement, but may be used during optimization.
 - **Partial Blockage** – an area with lower utilization.
 - **Halo** (padding) – an area outside a macro that should be kept clear of standard cells.



Placement Blockages and Halos

Design Import

Floorplan

Placement

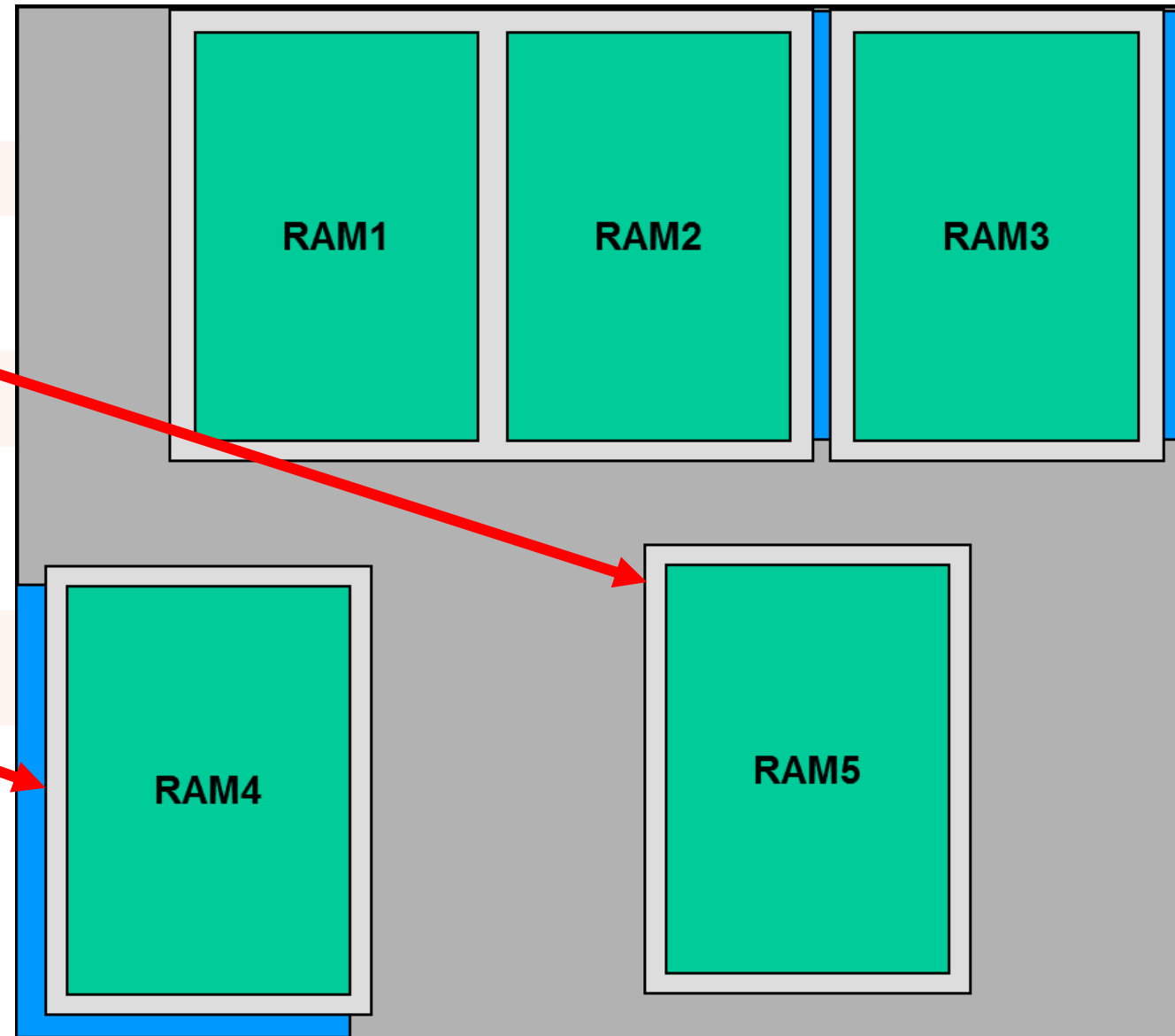
CTS

Route

Finish Design

Hard blockage
always created on
all four sides

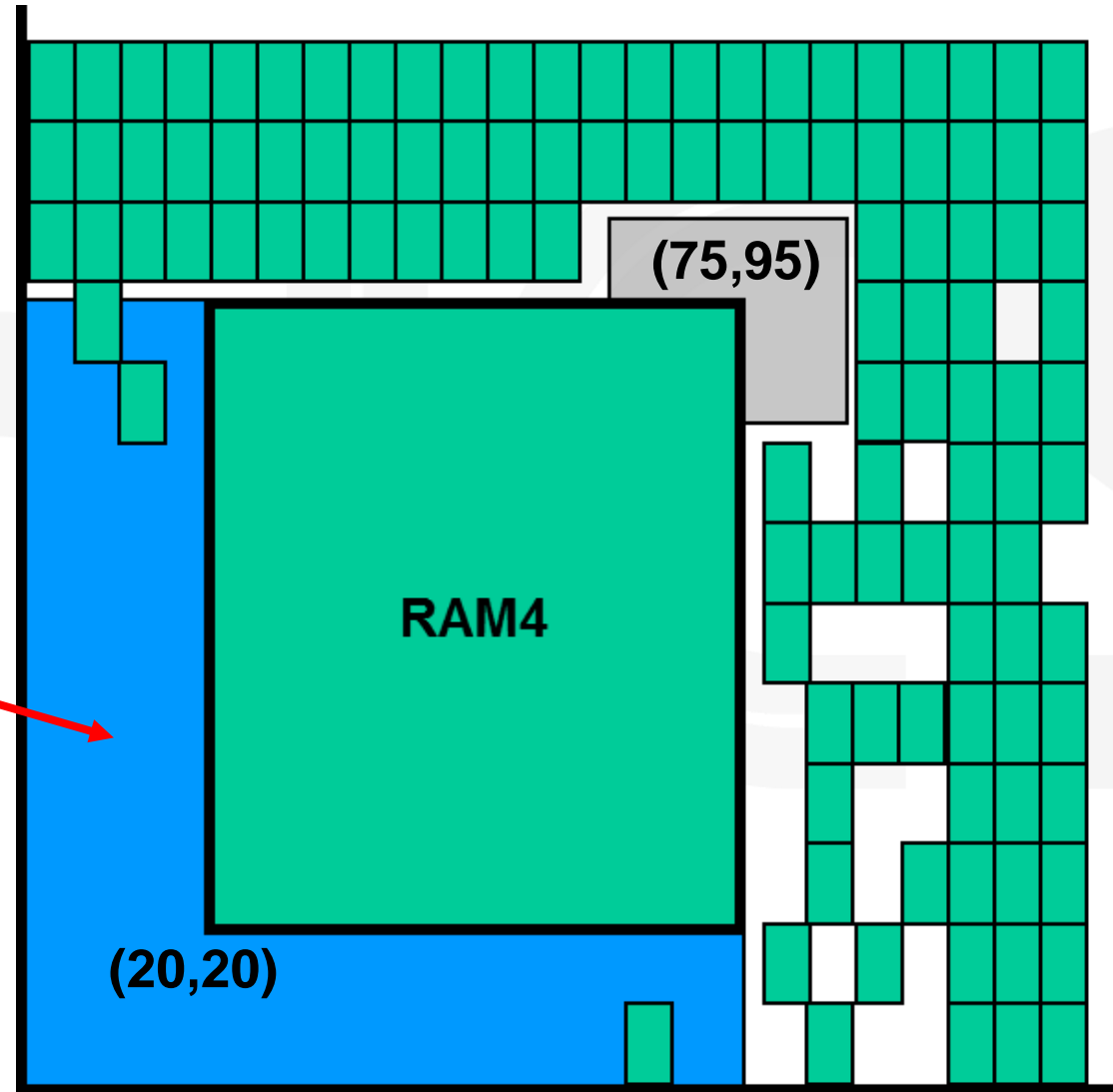
Soft blockage created
only for the channels
between the macros or
between the macro
and the core boundary



Routing Blockage

- Similar to placement blockage, **routing blockage** can be defined.
 - Blockage is defined for a given layer.

Routing
blockage



Design Import

Floorplan

Placement

CTS

Route

Finish Design

Guidelines for a good floorplan

Design Import

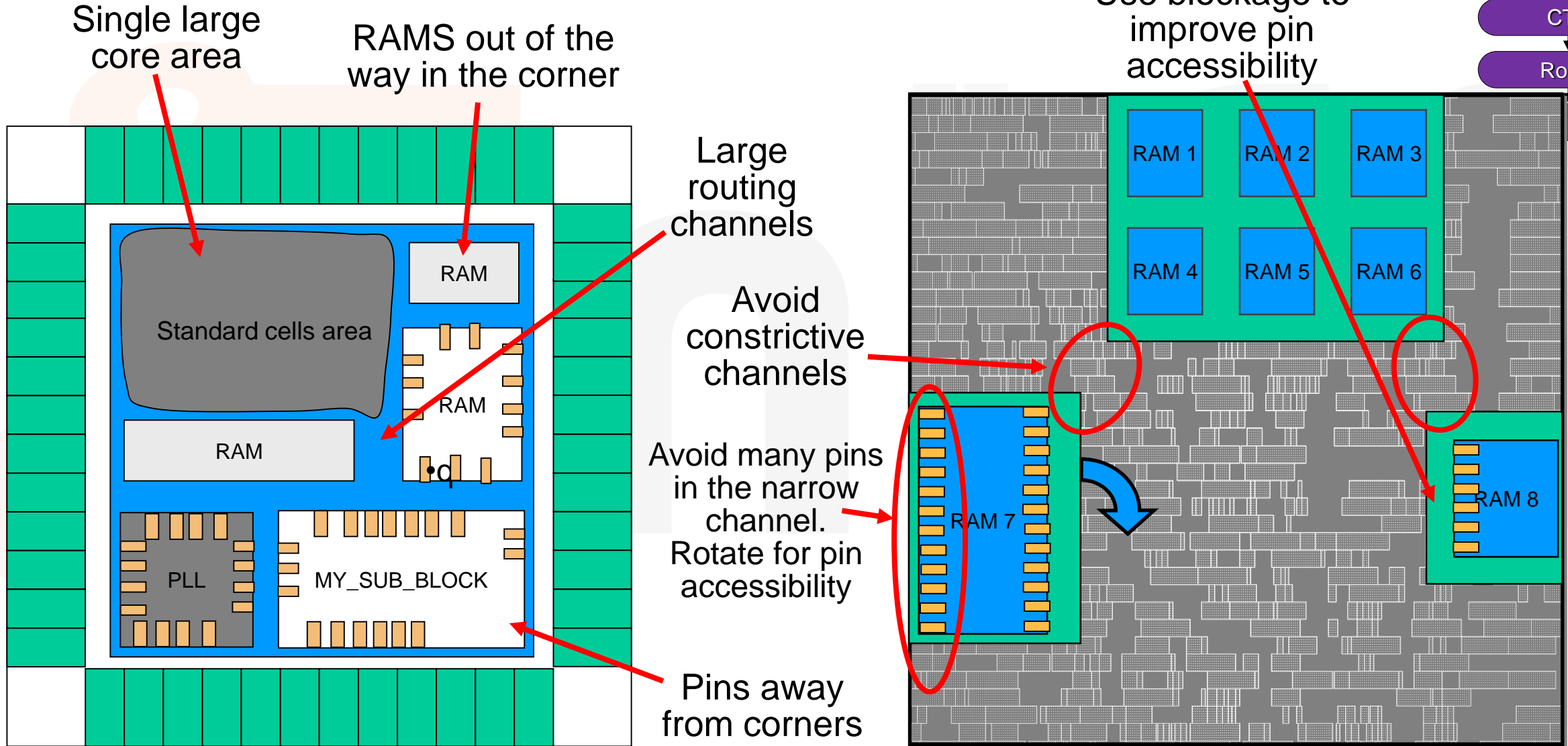
Floorplan

Placement

CTS

Route

Design





A bit about Hierarchical Design

Or how do you deal with a really big chip

Flat vs. Hierarchical Design

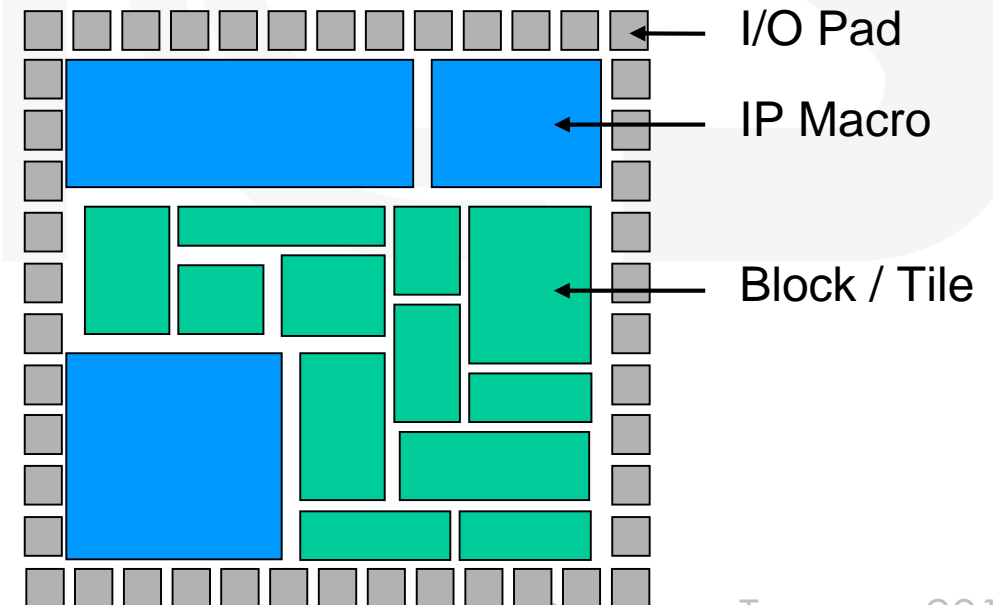
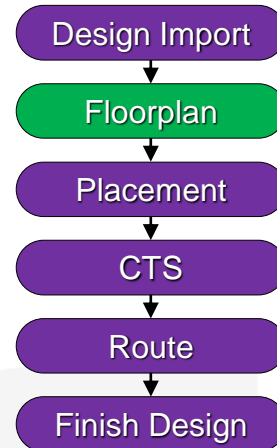
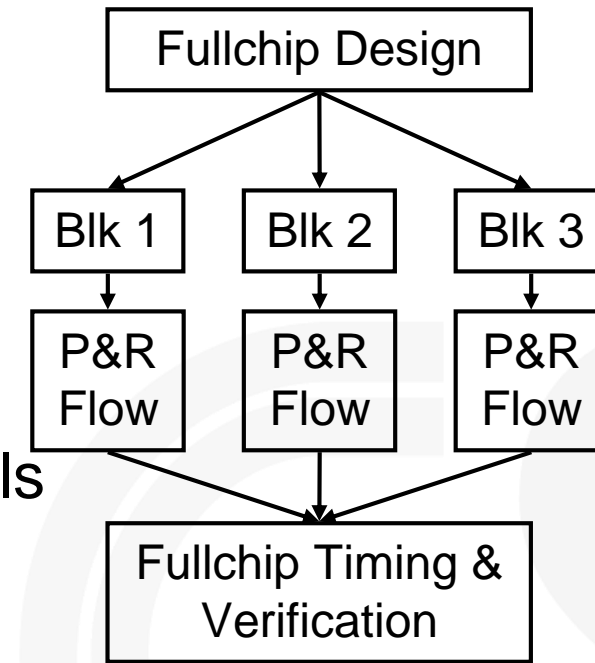
If the design is too big, partition it into **hierarchies**

- **Advantages**

- Faster **runtime**, less memory needed for EDA tools
- Faster **ECO** turn-around time
- Ability to do design **re-use**

- **Disadvantages**

- Much more difficult for fullchip **timing closure** (ILMs)
- More intensive **design planning** needed:
 - Feedthrough generation
 - Repeater insertion
 - Timing constraint budgeting
 - etc.



Hierarchical Design – Time Budgeting

Design Import

Floorplan

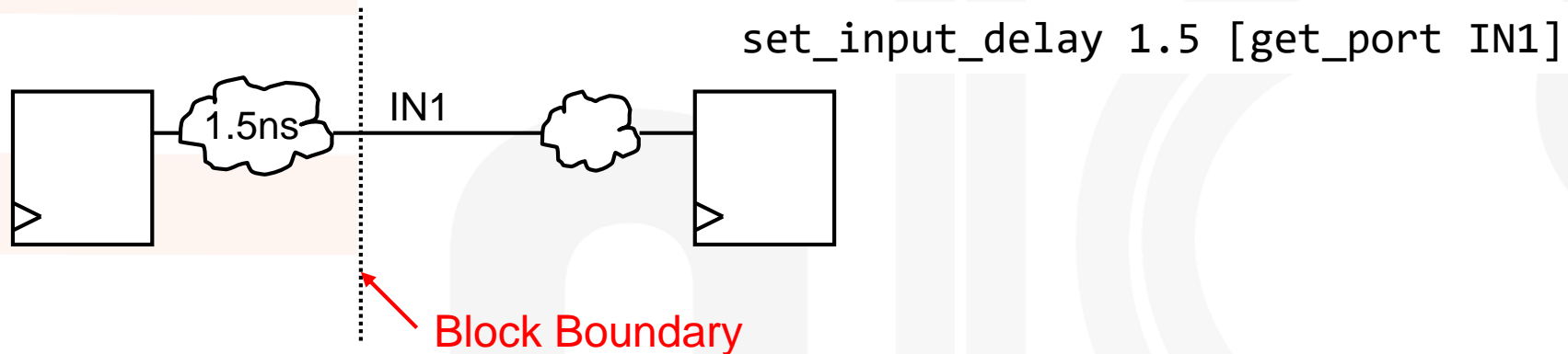
Placement

CTS

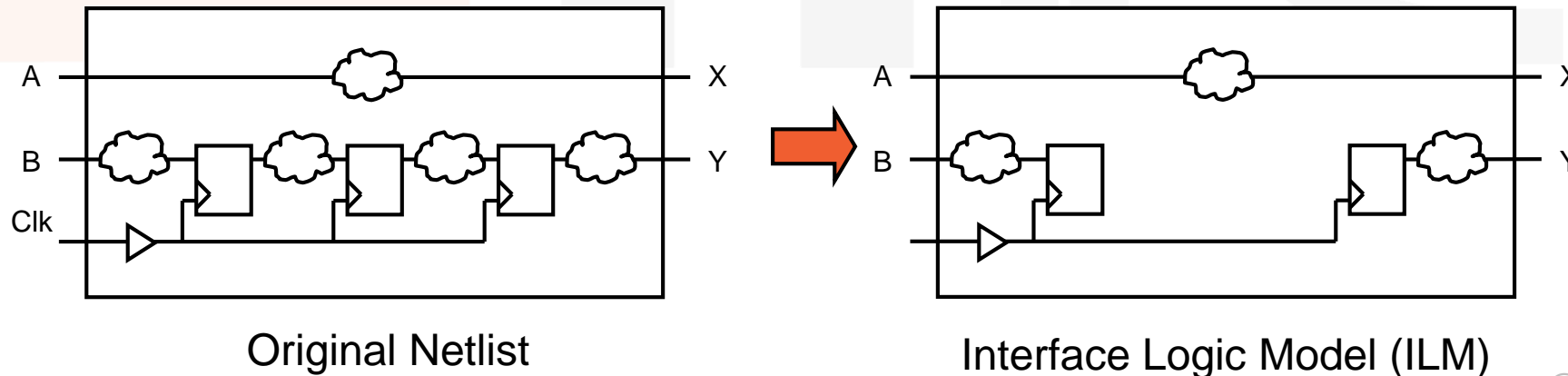
Route

Finish Design

- Chip level constraints must be mapped correctly to block level constraints as I/O constraints



- Interface Logic Models (ILMs) help simplify and speed-up design



Hierarchical Design – Pin Assignment

- **Pin constraints include parameters, such as:**

- Layers, spacing, size, overlap
- Net groups, pin guides

- **Pins can be assigned:**

- Placement-based (**flightlines**)
- Route-based (**trial route**, **boundary crossings**).

- **Pin guides**

- Can be used to influence automatic pin placement of particular net groups

Design Import

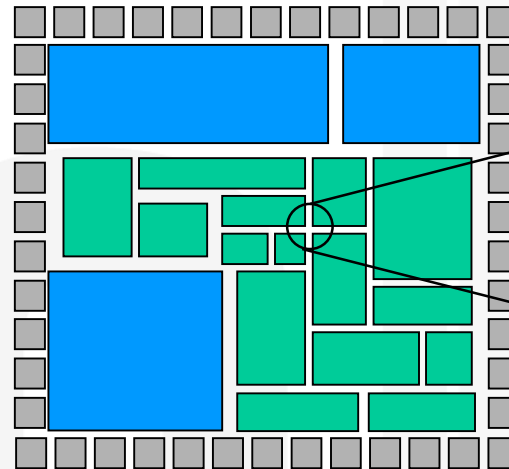
Floorplan

Placement

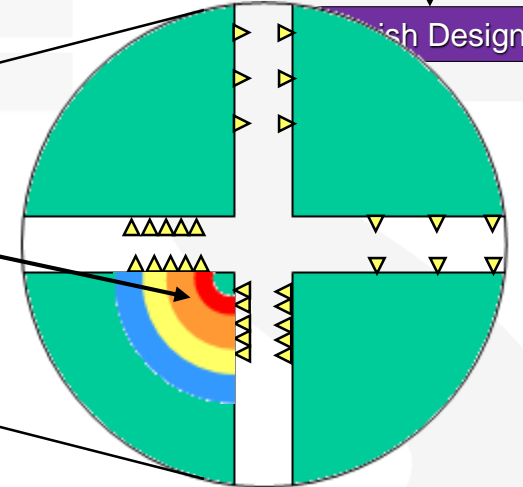
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Route

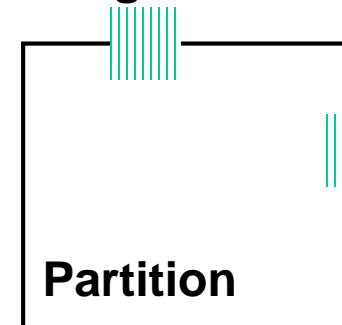
Finish Design



Pins at partition corners can make routing difficult



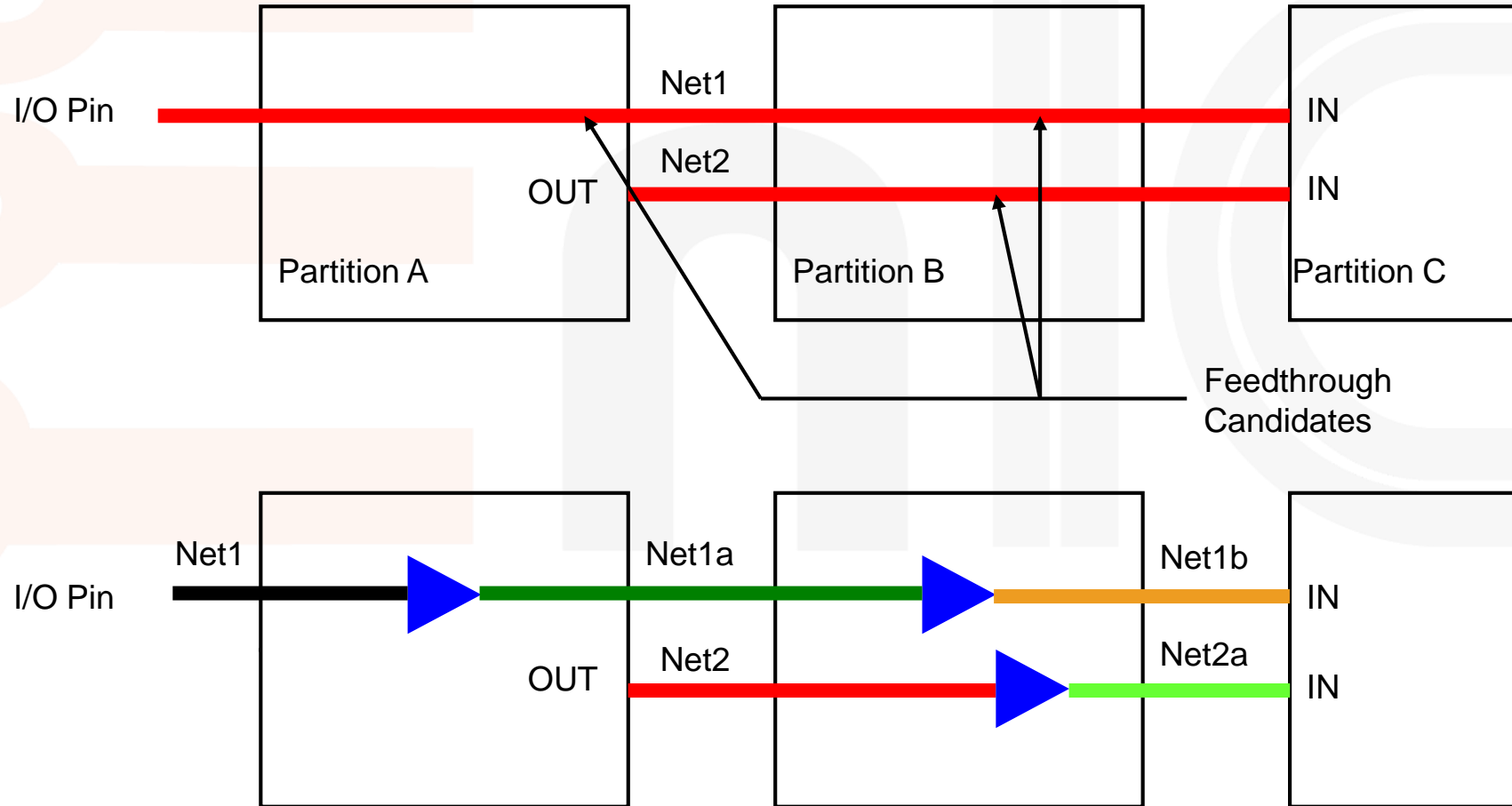
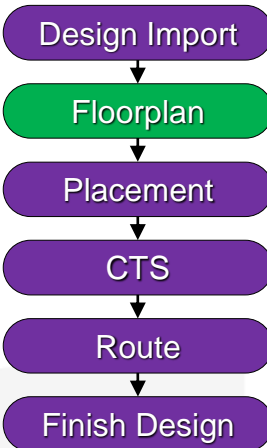
Pin guide 1



Pin guide 2

Hierarchical Design - Feedthrough

- For channel-less designs or designs with limited channel resources

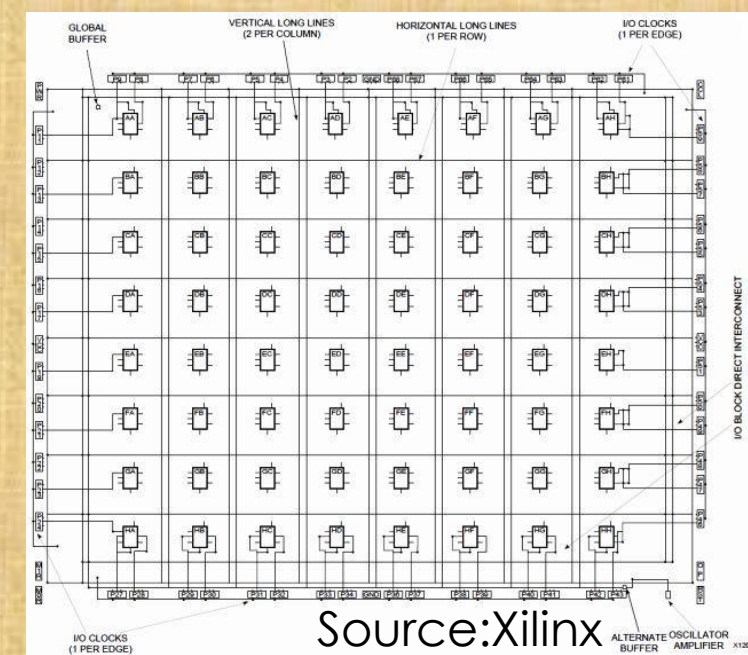


The Chip Hall of Fame

- Speaking about floorplans, this is one of the most essential attributes of an FPGA. And it started with the:

Xilinx XC2064 FPGA

- Ross Freeman, CEO of Xilinx, bet on Moore's law making transistors cheap enough to "waste".
- Release date: Nov. 1, 1985
- Process: Seiko 2um
- 64 Logic Cells and FFs, 38 I/O pins
- Originally called a "logic cell array" and programmed logic was drawn by hand.
- Xilinx was the world's first fabless IC vendor.



2017 Inductee to the IEEE Chip Hall of Fame



Power Planning

Power Consumption and Reliability

Dynamic Power



Static Power
(Leakage Power)

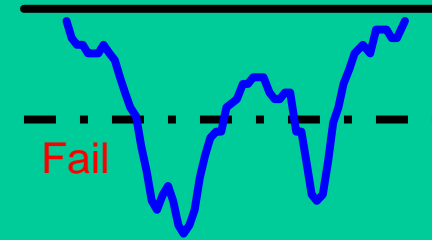


Floorplan
+
Design of the grid

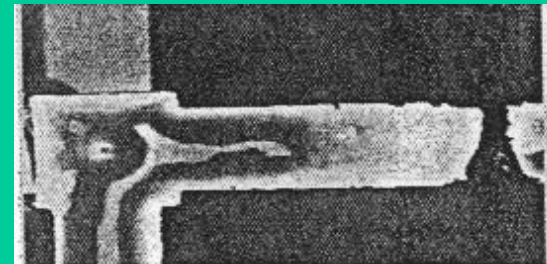
Average or
Instantaneous
Power problem

Power density
problem in the
Long run

IR-Drop /
Voltage Droop



Electromigration
(EM)



Design Import

Floorplan

Placement

CTS

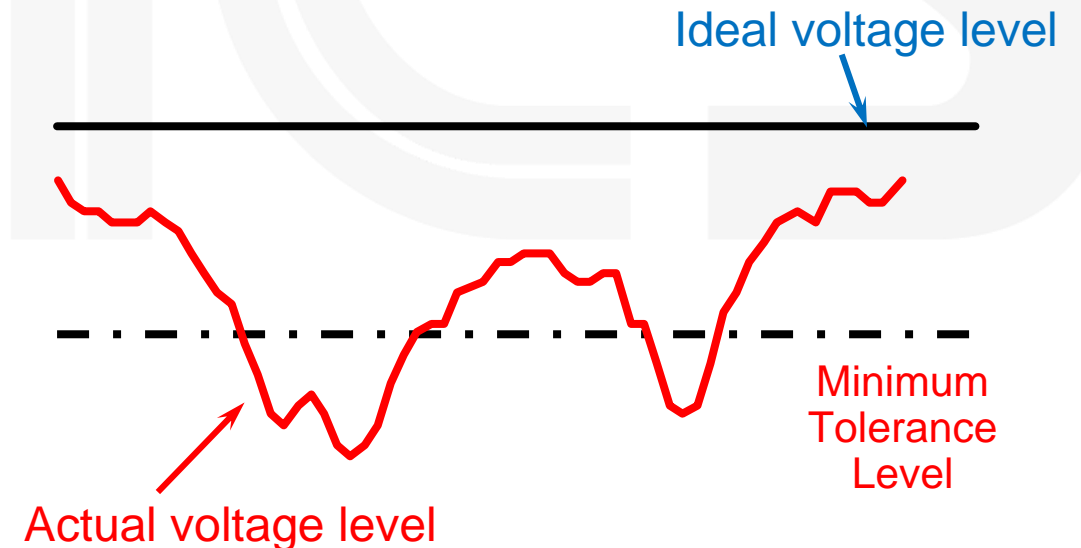
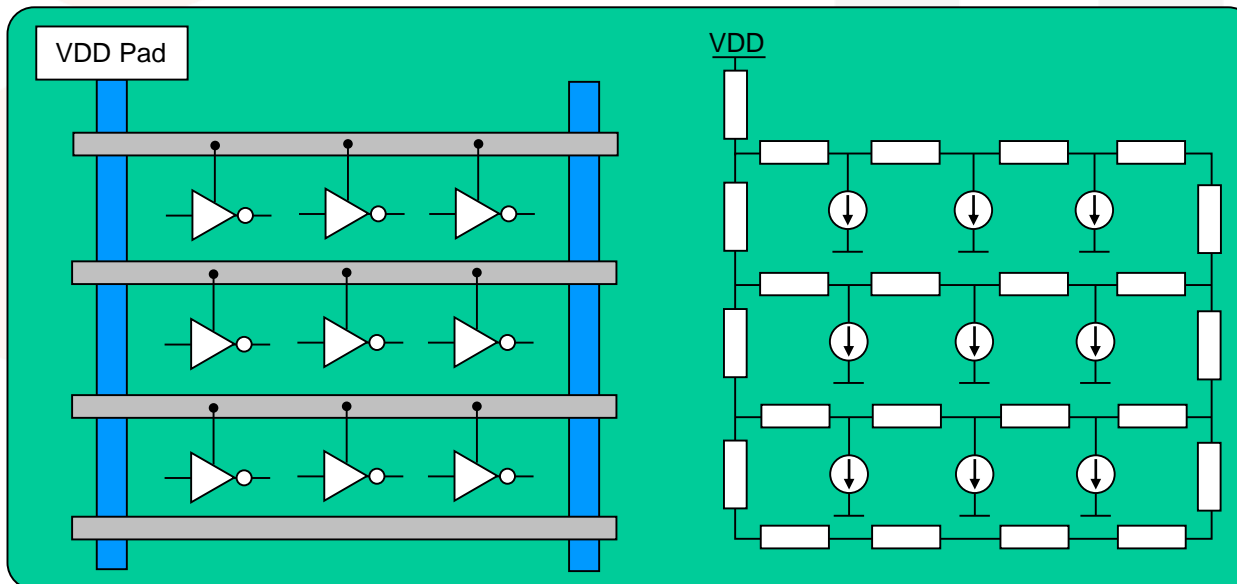
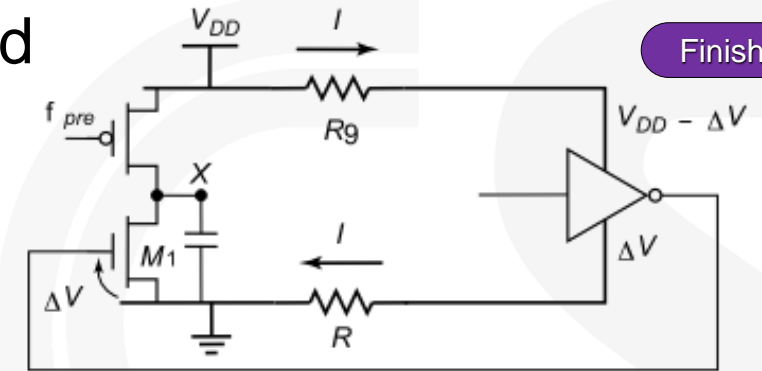
Route

Finish Design

IR Drop

- The drop in supply voltage over the length of the supply line

- A **resistance matrix** of the power grid is constructed
- The **average current** of each gate is considered
- The matrix is solved for the current at each node, to determine the **IR-drop**.



Design Import

Floorplan

Placement

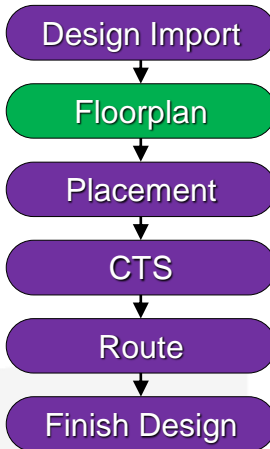
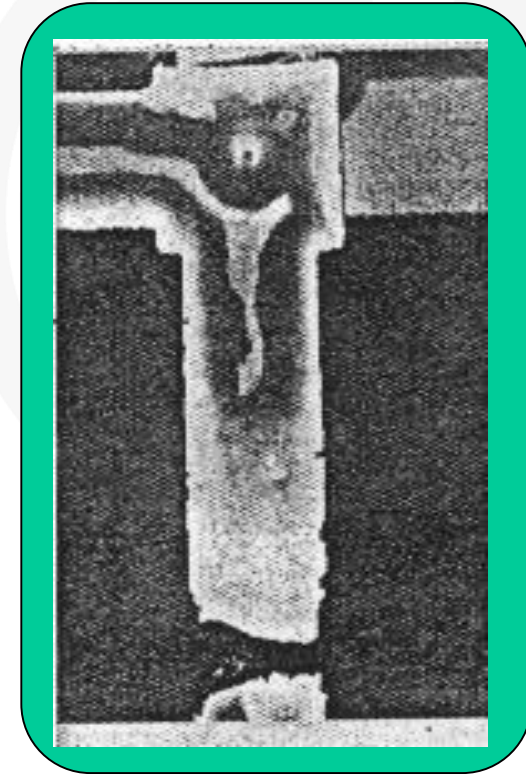
CTS

Route

Finish Design

Electromigration (EM)

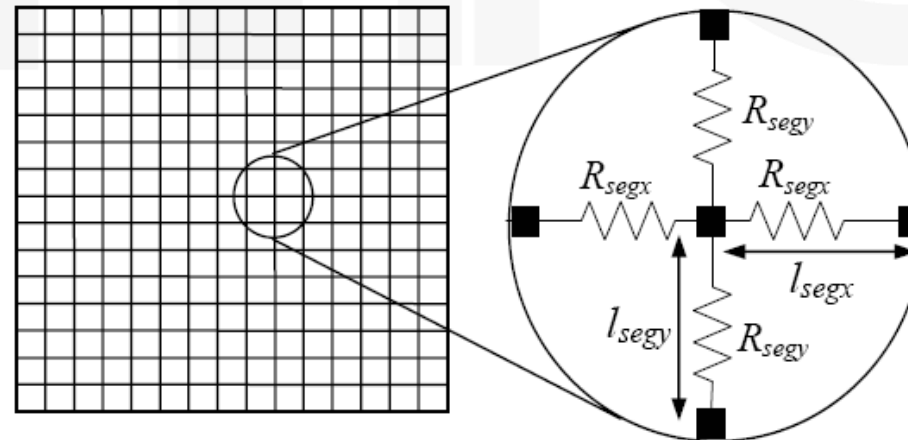
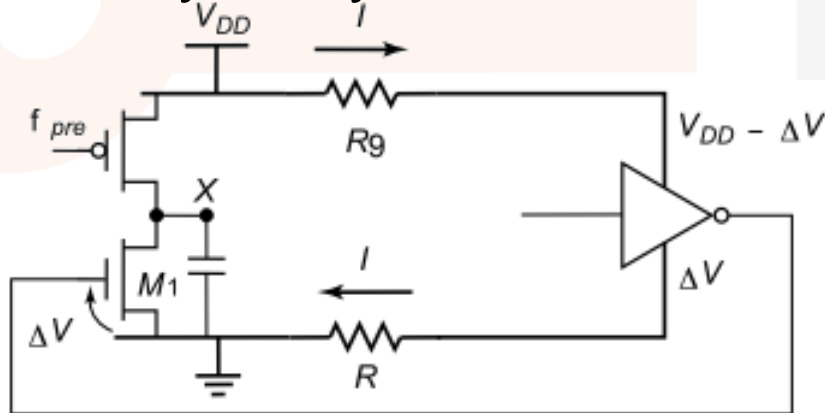
- **Electromigration** refers to the gradual displacement of the metal atoms of a conductor as a result of the current flowing through that conductor.
 - Transfer of electron momentum
- **Can result in catastrophic failure** do to either
 - **Open** : void on a single wire
 - **Short** : bridging between to wires
- **Even without open or short, EM can cause performance degradation**
 - Increase/decrease in wire RC



Power Distribution

- **Power Distribution Network functions**

- Carry **current** from pads to transistors on chip
- Maintain stable **voltage** with low noise
- Provide average and peak **power** demands
- Provide current **return paths** for signals
- Avoid **electromigration** & self-heating **wearout**
- Consume little chip **area** and **wire**
- Easy to lay out



More (Wider) Power Lines:

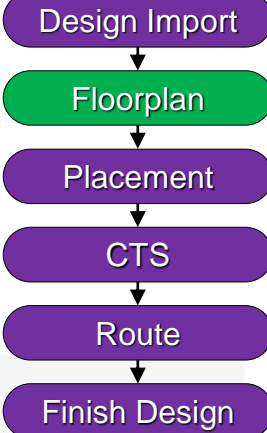
- Less Static (IR) drop
- Less Dynamic (dI/dt) drop
- Less Electromigration

BUT

More (Wider) Power Lines:

- Fewer (signal) routing resources
(i.e., higher congestion)

Power Distribution Challenge



- Assume we have a 1mm long power rail in M1.

- Square resistance is given to be 0.1 ohm/square

- If we make a 100nm wide rail, what is the **resistance** of the wire?

$$R = R_{\square} L/W = 0.1 \Omega/\square \cdot \frac{10^{-3} m}{100 \cdot 10^{-9} m} = 1000 \Omega$$

- Now, given a max current of 1mA/1um, due to **Electromigration**, what is the **IR drop** when conducting such a current through this wire?

$$I_{\max} = \frac{1 \text{mA}}{1 \mu\text{m}} \cdot 100 \text{nm} = 0.1 \text{mA}$$

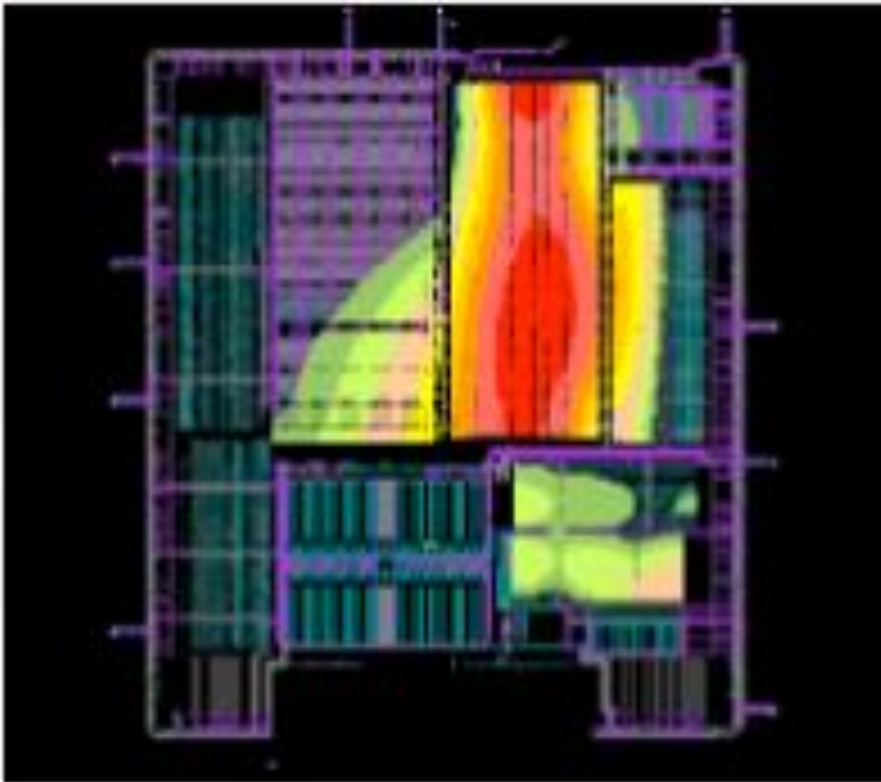
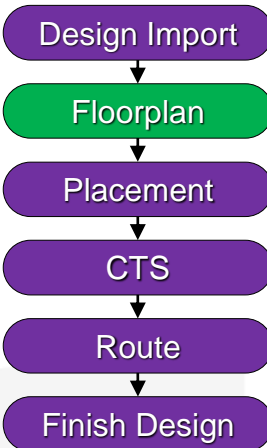
$$IR_{\text{drop}} = I_{\max} \cdot R_{\text{wire}} = 10^{-4} \cdot 10^3 = 100 \text{mV}$$

- So what do we do?

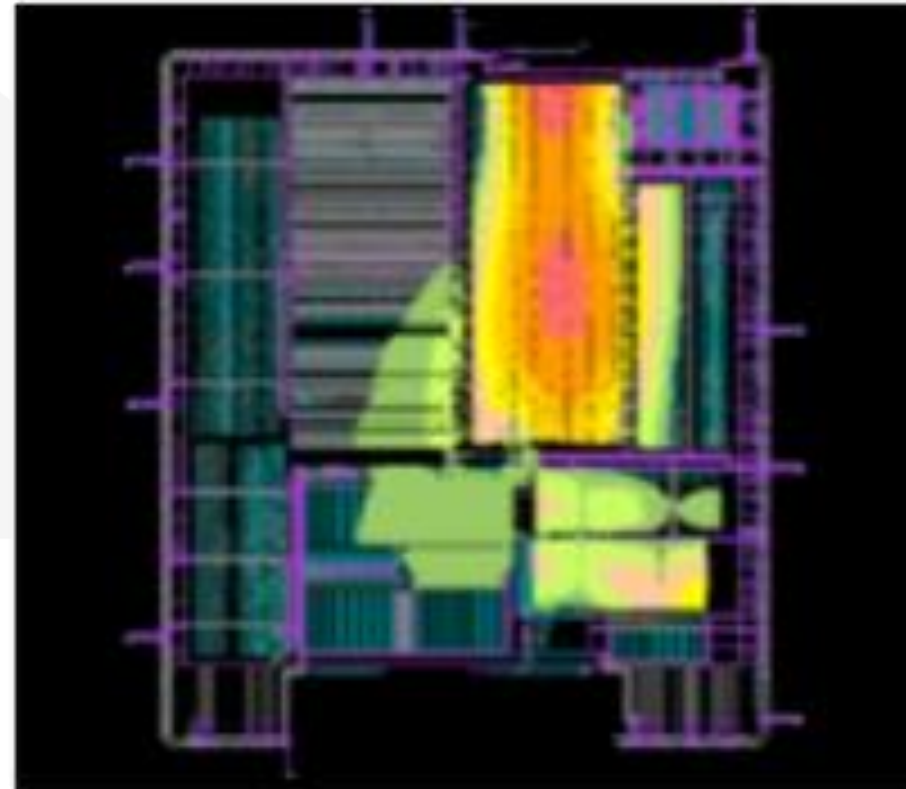
- Make the power rails as wide and as thick as possible!

Hot Spots

- We generally map the **IR drop** of a chip using a color map to highlight “hot spots”, where the **IR drop** is bad.



Initial IR Drop Mapping

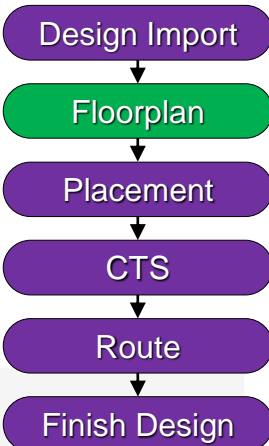
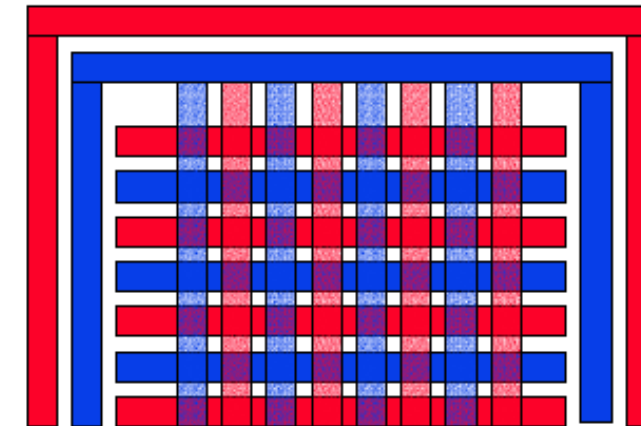
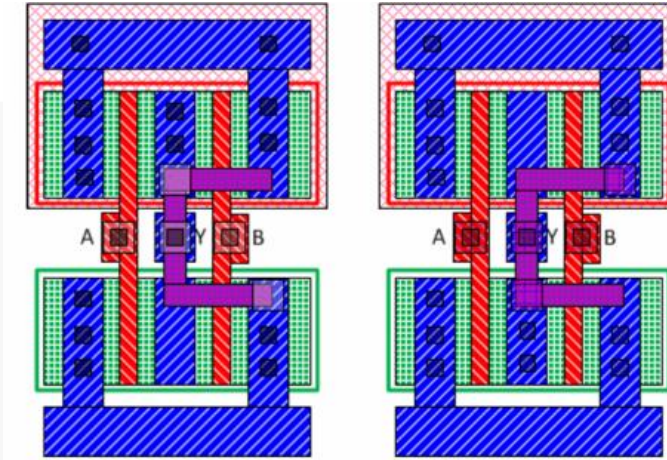


After adding a single wire!

Source:
Cadence

Power and Ground Routing

- Each standard cell or macro has power and ground signals, i.e., **VDD** (power) and **GND** (ground)
 - They need to be connected as well
- Power/Ground **mesh** will allow multiple paths from P/G sources to destinations
 - Less series **resistance**
 - Hierarchical power and ground **meshes** from upper metal layers to lower metal layers
 - **Multiple vias** between layers
- You can imagine that they are **HUGE NETWORKS!**
 - In general, P/G routings are pretty regular
 - P/G routing resources are usually reserved



Standard Approaches to Power Routing

- **Power Grid**

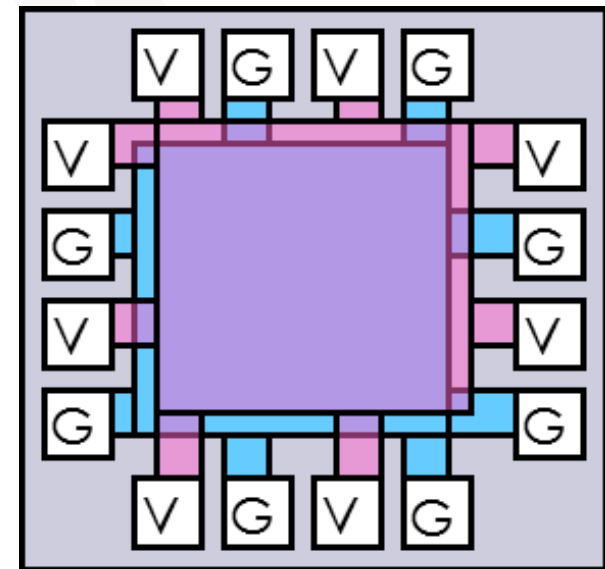
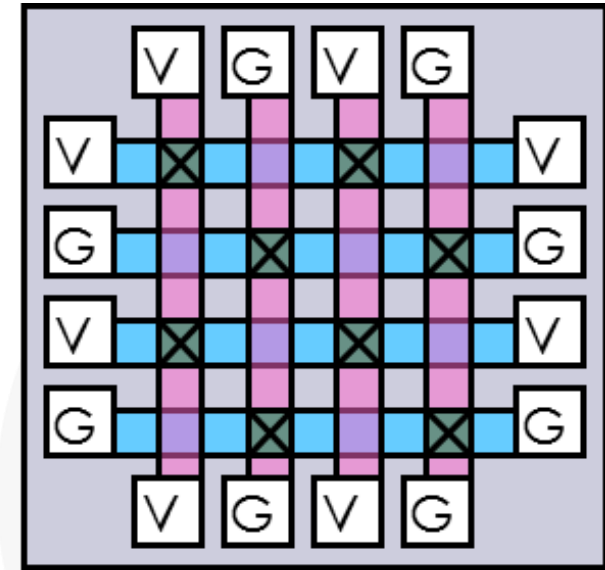
- Interconnected vertical and horizontal power bars.
- Common on most high-performance designs.
- Often well over half of total metal on upper thicker layers used for VDD/GND.

- **Dedicated VDD/GND planes.**

- Very expensive.
- Only used on Alpha 21264, Dropped on subsequent Alphas.
- Simplified circuit analysis.

- **Some thoughts/trends:**

- P/G I/O pad co-optimization with classic physical design
- Decoupling capacitors to reduce P/G related voltage drop
- Multiple voltage/frequency islands make the P/G problem and clock distributions more challenging.



Design Import

Floorplan

Placement

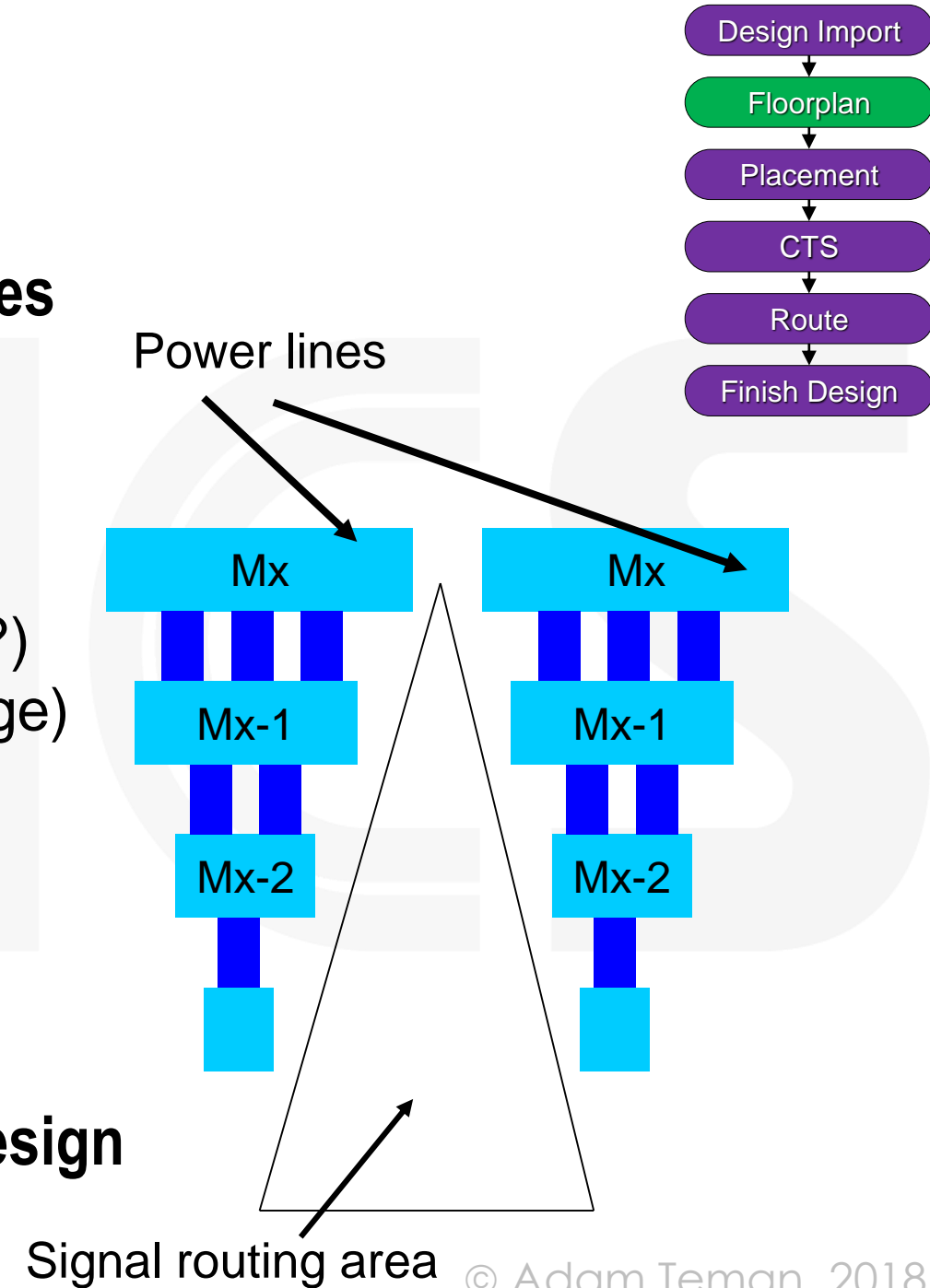
CTS

Route

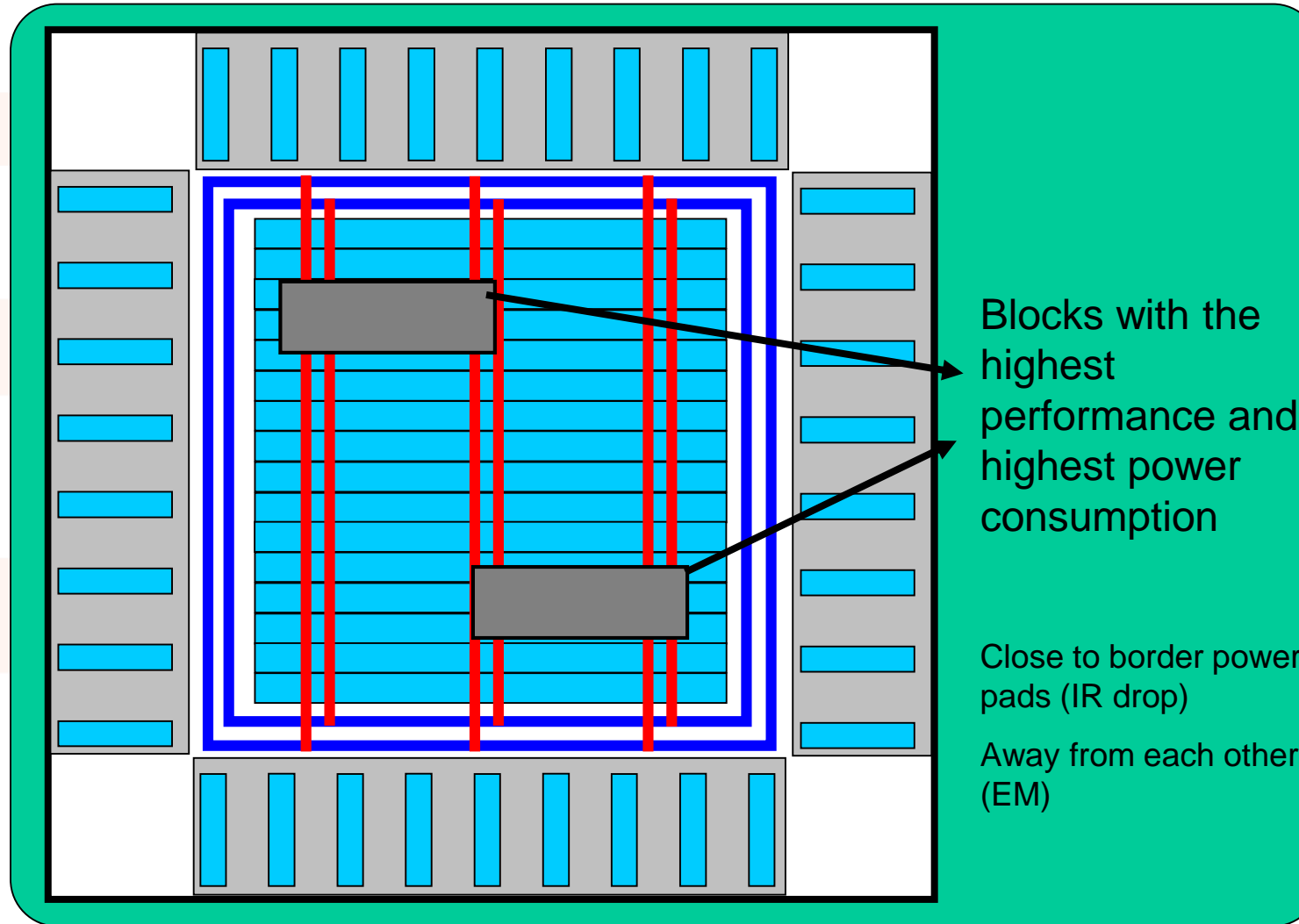
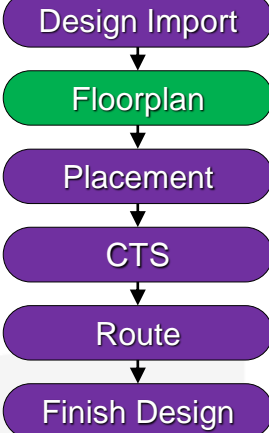
Finish Design

Power Grid Creation

- **Tradeoff IR drop and EM versus routing resources**
 - Require power budget
 - Initial power estimation
 - Average current, max current density
- **Need to determine**
 - General grid structure (gating or multi-voltage?)
 - Number and location of power pads (per voltage)
 - Metal layers to be used
 - Width and spacing of straps
 - Via stacks versus available routing tracks
 - Rings / no rings
 - Hierarchical block shielding
- **Run initial power network analysis to confirm design**



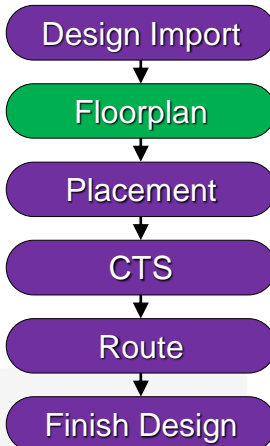
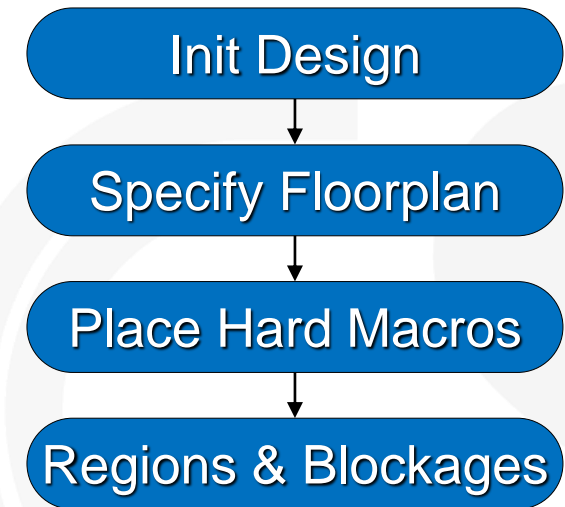
Power Grid Creation – Macro Placement



Summary – Floorplanning in Innovus

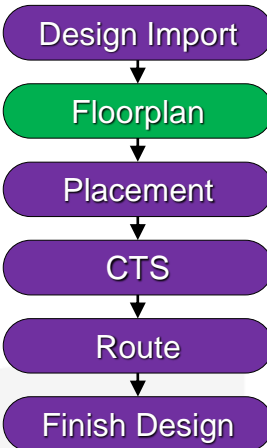
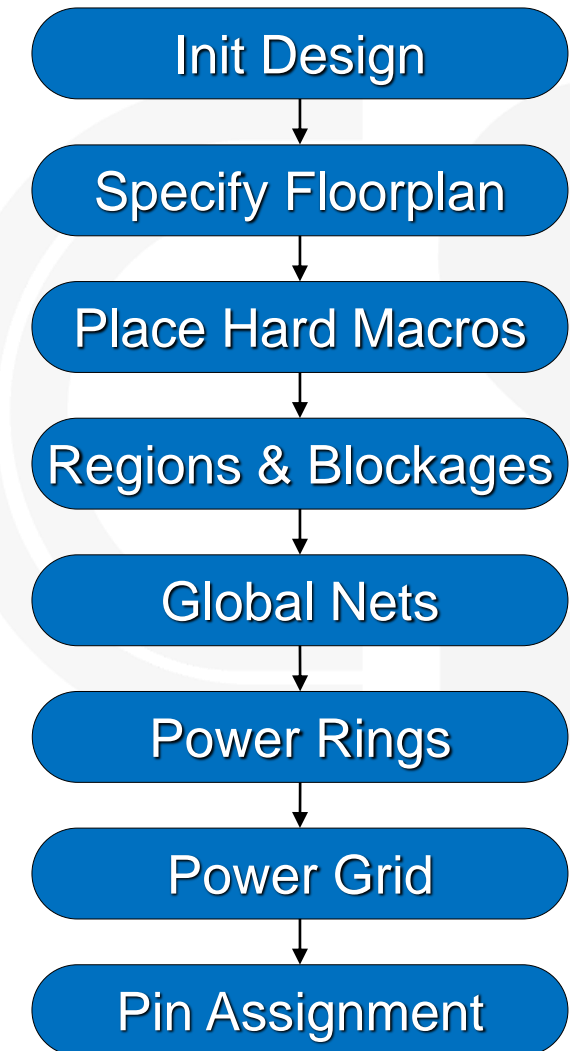
- Floorplanning is very specific to each design and can include many commands, but the general flow is:

- Initialize Design:
 - Define Verilog netlist, MMMC (timing, SDC, extraction, etc.), LEF, IO placement
- Specify floorplan
 - Define floorplan size, aspect ratio, target utilization
- Place hard macros
 - Absolute or relative placement
 - Define halos and blockages around macros
- Define regions and blockages
 - If necessary, define placement regions and placement blockage
 - If necessary, define routing blockage



Summary – Floorplanning in Innovus

- Define Global nets
 - Tell the tool what the names of the global nets (VDD, GND) are and what their names are in the IPs.
- Create Power Rings
 - Often rings for VDD, GND are placed around the chip periphery, as well as around each individual hard IP.
- Build Power Grid
 - Connect standard cell 'follow pins'
 - Build power stripes on metal layers
 - Make sure power connects to hard IPs robustly
- Assign Pins
 - If working on a block (not fullchip), assign pins to the periphery of the floorplan.



Main References

- **IDESA**
- **Rabaey**
- **CMOS VLSI Design**
- **EPFL Tutorial**
- **Experience!**

anics