

# Digital Microelectronic Circuits

**(361-1-3021 )**

Presented by: Adam Teman

**Lecture 10:**

**Dynamic  
Logic**

# Motivation

- ❑ Last lecture, we learned about *Pass Transistor Logic*.
- ❑ Using this technique (i.e. passing a signal through a diffusion input in addition to the gate input), we were able to reduce the number of transistors needed to implement several logic gates.
- ❑ However, pass transistors presented several disadvantages, such as  $V_T$  drop, static power dissipation, loss of regenerative property, and in certain situations, slow transitions.
- ❑ In this lecture, we will discuss another concept – *dynamic logic* – and its implementation into an efficient and very fast logic family.

# *What will we learn today?*

**10.1 Dynamic CMOS**

**10.2 Charge Loss**

**10.3 Charge Sharing**

**10.4 Cascading Dynamic Gates**

**10.5 Logical Effort of Domino**

# 10.1

## 10.1 Dynamic CMOS

## 10.2 Charge Loss

## 10.3 Charge Sharing

## 10.4 Domino Logic

## 10.5 LE of Domino



So now we'd like to reduce some gates and speed up our calculations. It's time for

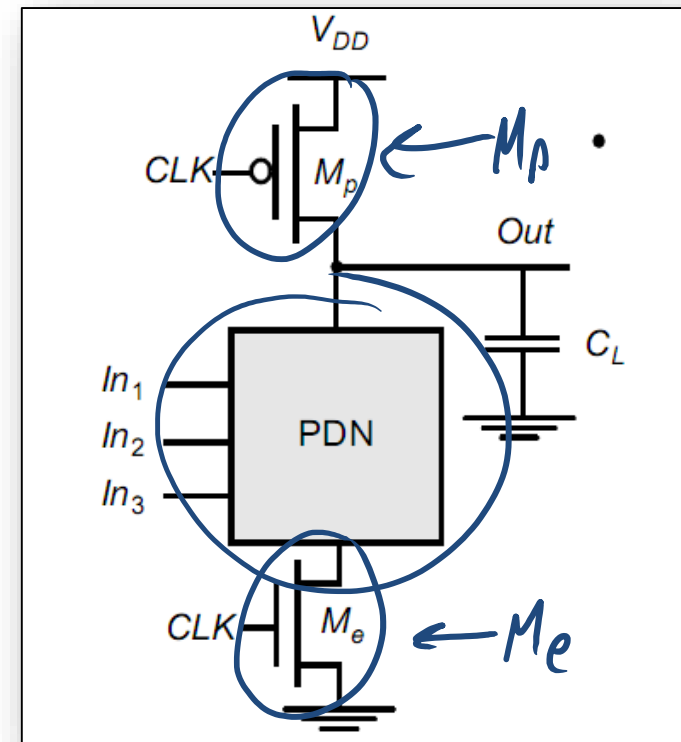
# ***DYNAMIC LOGIC***

# Introduction

- ❑ So far, we've seen that:
  - » *Standard CMOS* require  $2N$  transistors for  $N$  inputs.
  - » *Pseudo nMOS* requires only  $N+1$  transistors, but has *high static power consumption*.
  - » *PTL* is only efficient for certain functions
- ❑ An alternative logic style called *Dynamic Logic* provides:
  - »  $N+2$  Transistors for  $N$  Inputs
  - » *Low Static Power Consumption*
  - » *High Operation Speed*
- ❑ *Dynamic Logic* provides a very different approach to gate implementation, defining it as a completely different style than the previously discussed *Static* families.

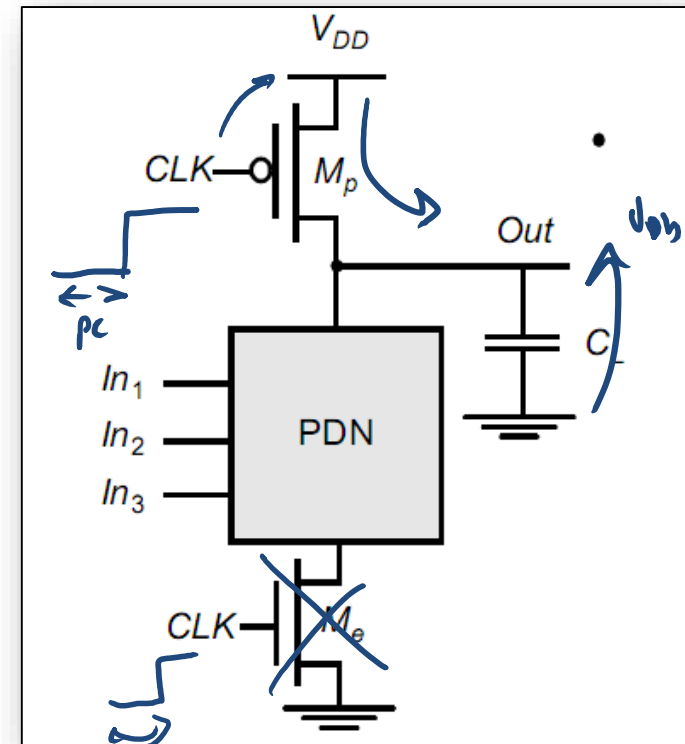
# Dynamic Logic Concept

- ❑ *Dynamic Circuits* operate in **two phases**:
  - » **Precharge**: set an *initial output state*
  - » **Evaluation**: change the precharged output to the *legal state*.
- ❑ This is done with a basic architecture that includes:
  - » A standard **PDN** network
  - » Complementary **precharge switches**
- ❑ This is an “***n-type***” network.  
The same can be accomplished using a “***p-type***” ***Pull-Up*** network.



# Dynamic Logic Concept - Precharge

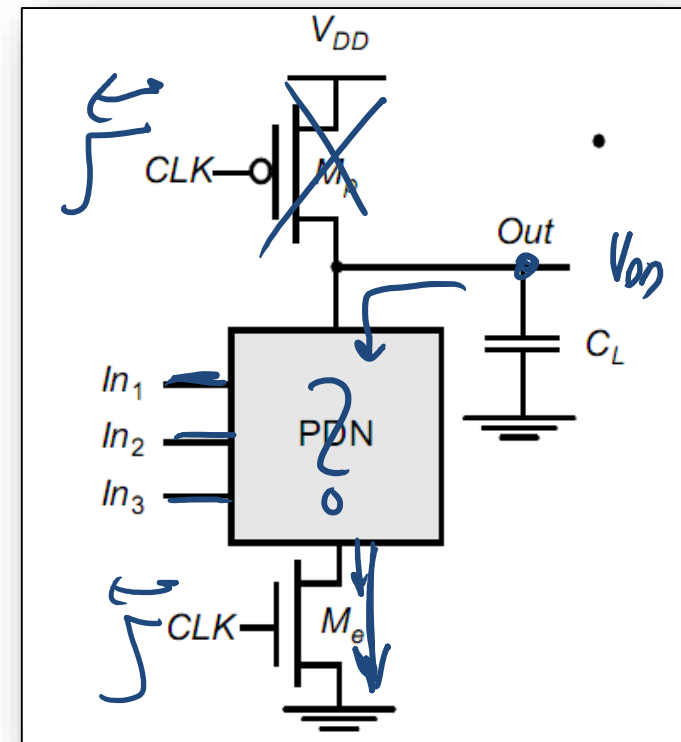
- ❑ **Precharge** occurs when the **clock is low**, **blocking** the **discharge path** and **enabling** the **pull up path**.
- ❑ The **output capacitance** is charged to **'1'** through the **top pMOS** (the **Precharge Transistor**).
- ❑ The **bottom nMOS** eliminates **static current** and **ratioed behavior**.





# Dynamic Logic Concept - Evaluation

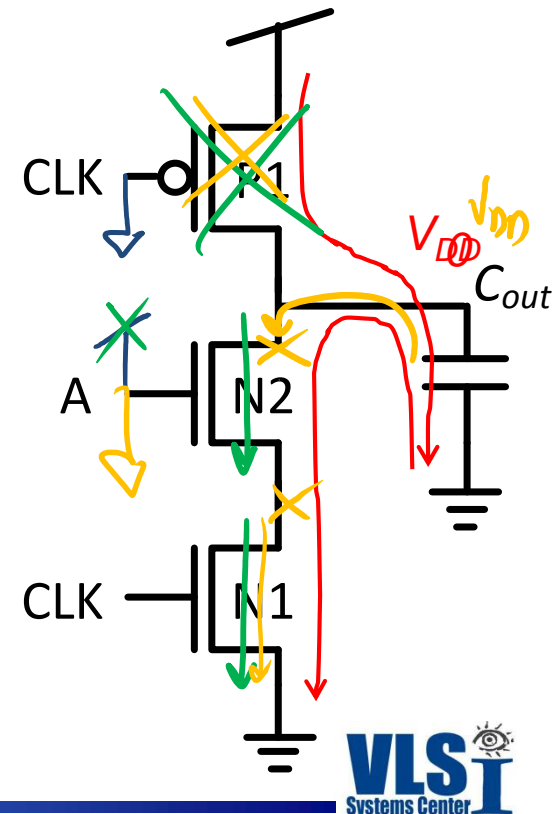
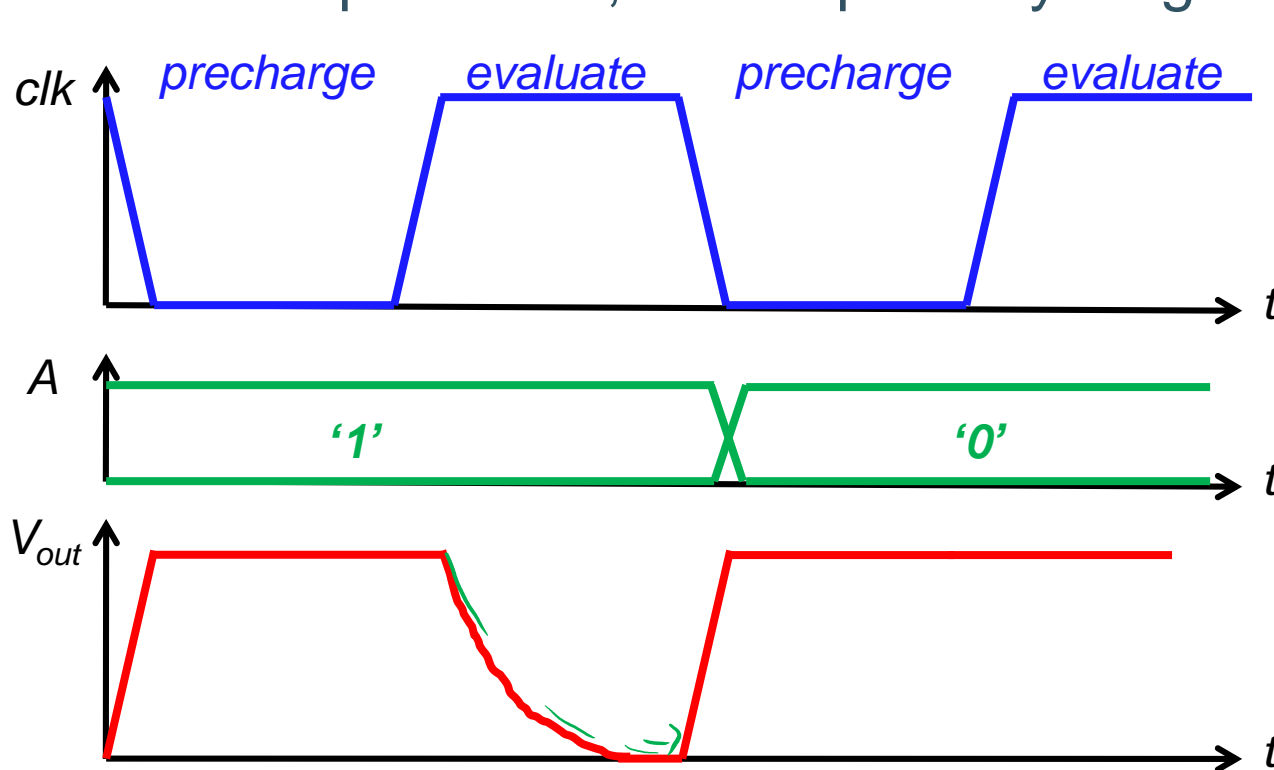
- ❑ **Evaluation** occurs when the *clock is high*.
- ❑ The **Precharge Transistor** is turned **off**, blocking any additional charge from *flowing to the output capacitance*.
- ❑ The **bottom nMOS** (the **Evaluation Transistor**) is turned **on**, enabling a *conditional path to ground*.
- ❑ The *output is discharged*, depending on the *input values* and the *combinational function* of the **PDN**, similar to *static logic* families.





# Example – Dynamic Inverter

- ❑ When the clock is low, the capacitance is charged.
- ❑ When the clock goes high, the output is discharged if the input is high.
- ❑ If the input is low, the output stays high.

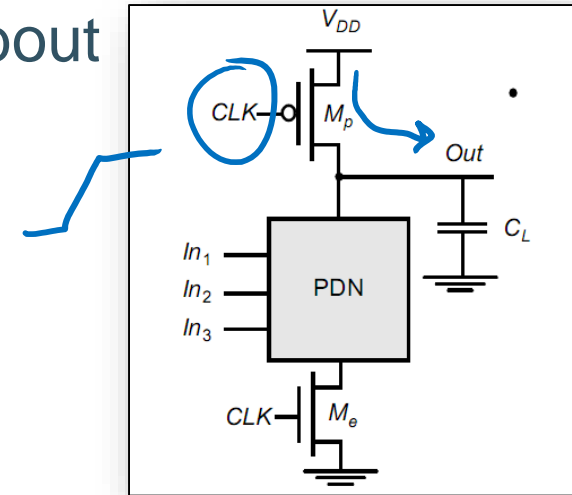


# Dynamic Logic Properties

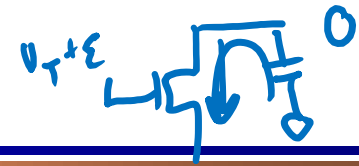
$$P_{dyn} = \alpha f C V_m^2$$

□ The operation of **Dynamic Logic** brings about a number of important properties:

- »  **$N+2$  Transistors** are required for gate implementation.
- » The logic is **Non-Ratioed** (i.e. **sizing** doesn't affect **functionality**).
- » **Static Power Consumption** is **low**, but **Dynamic Power Consumption** is significantly **higher** than **Standard CMOS**.
- » The **Switching Speeds** are **higher** than **Standard CMOS** due to **Reduced Load Capacitance**, **Zero Short-Circuit Current** and ability to **Optimize Only One Swing** ( $t_{pHL}$ ).

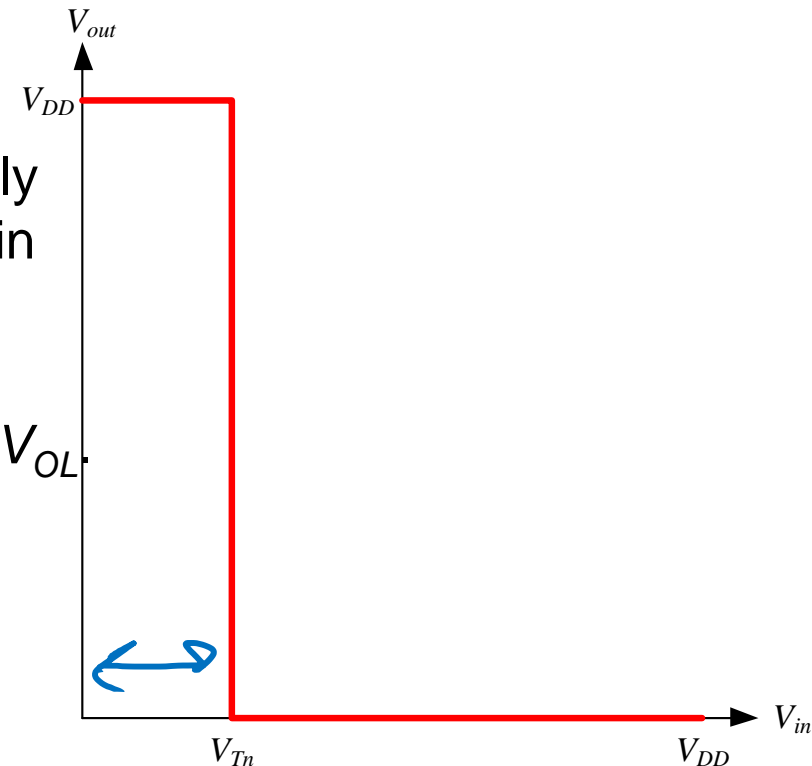


# Dynamic Logic VTC



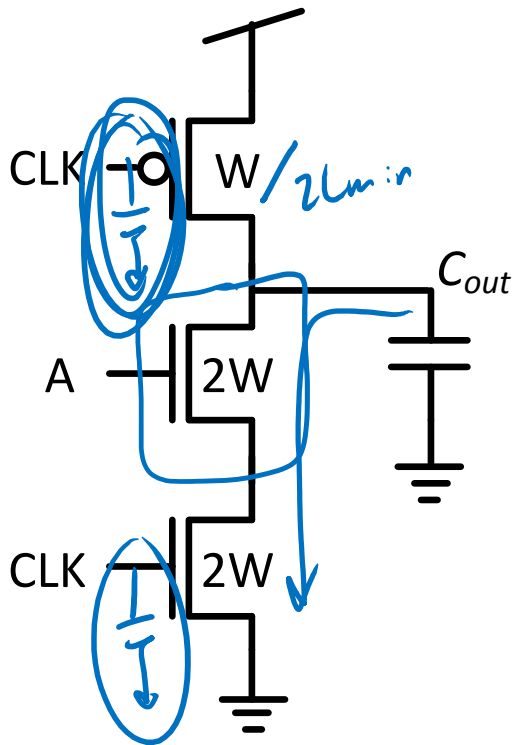
## □ An Interesting (Bizarre) VTC

- » Remember – assume DC...
- » Until  $V_{Tn}$ , the output is  $V_{OH}$ .
- » Once we pass  $V_{Tn}$ , there is no partially open pMOS combating the PDN, so in a DC perspective, output will fully discharge.
- » The VTC drops STRAIGHT down to  $V_{OL}$ .
- » (If not DC, but bounded with time, the VTC will be more gradual...)



□  $NM_L = V_{Tn}$ . This is very low!

# Logical Effort of Dynamic Logic



$t_{pHL}:$

$$R_{eq} = 2R_n / 2 = R_{inv}$$

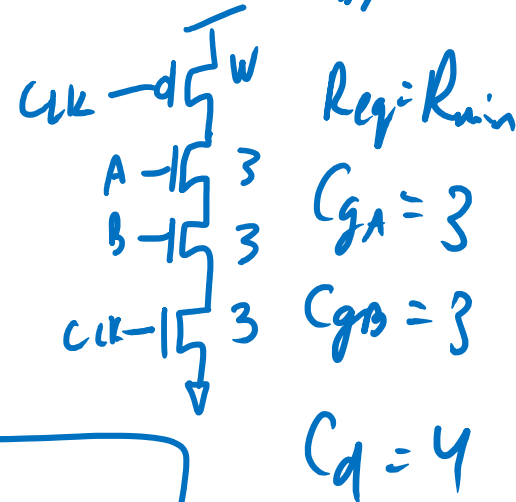
$$C_g(A) = 2C_{gmin}$$

$$C_d = 3C_{dmin}$$

$t_{pLH}: p = 0, LE = 0$

$$p = \frac{R_{gate}}{R_{inv}} \cdot \frac{C_{d,gate}}{C_{d,min}} = \frac{3}{3} = 1$$

$$LE = \frac{R_{gate}}{R_{inv}} \cdot \frac{C_{g,gate}}{C_{g,min}} = \frac{2}{3}$$

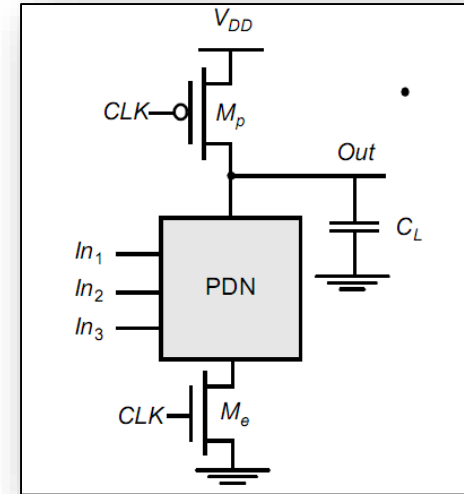


- Therefore, we get a very fast gate!
- For a 2-input *NAND*, we get:

$$p_{NAND} = \frac{4}{3}, LE_{NAND} = 1$$

# Dynamic Logic Problems

- ❑ The basic consideration of using *Dynamic* vs. *Static Logic* is *Speed* vs. *Power*.
- ❑ However, *High Output Degradation* can occur in *Dynamic Logic* in the following cases:
  - » Input Glitches ✓
  - » Leakage Currents ✓
  - » Charge Sharing ✓
  - » Cascading dynamic gates ✓



# 10.2

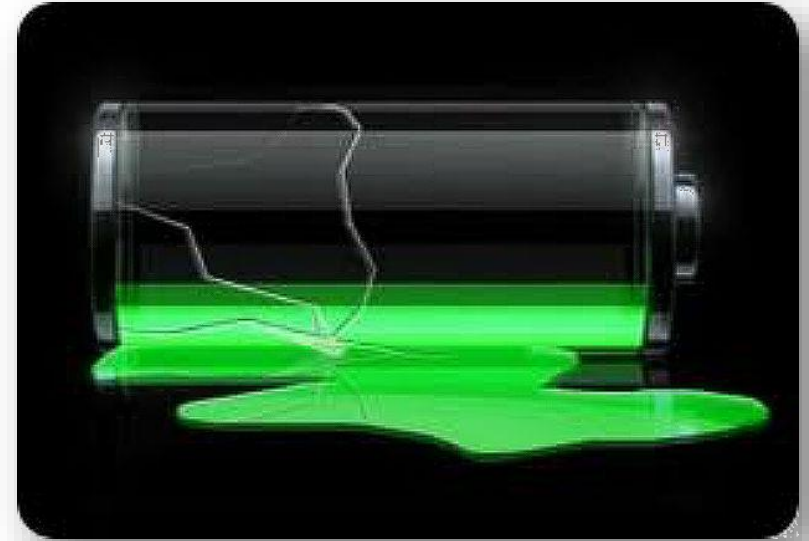
**10.1 Dynamic CMOS**

**10.2 Charge Loss**

**10.3 Charge Sharing**

**10.4 Domino Logic**

**10.5 LE of Domino**

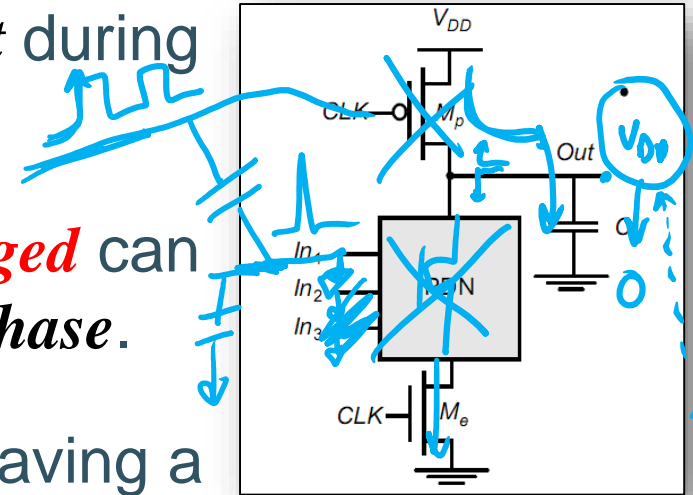


The Big Problem with Dynamic gates is their

***CHARGE LOSS***

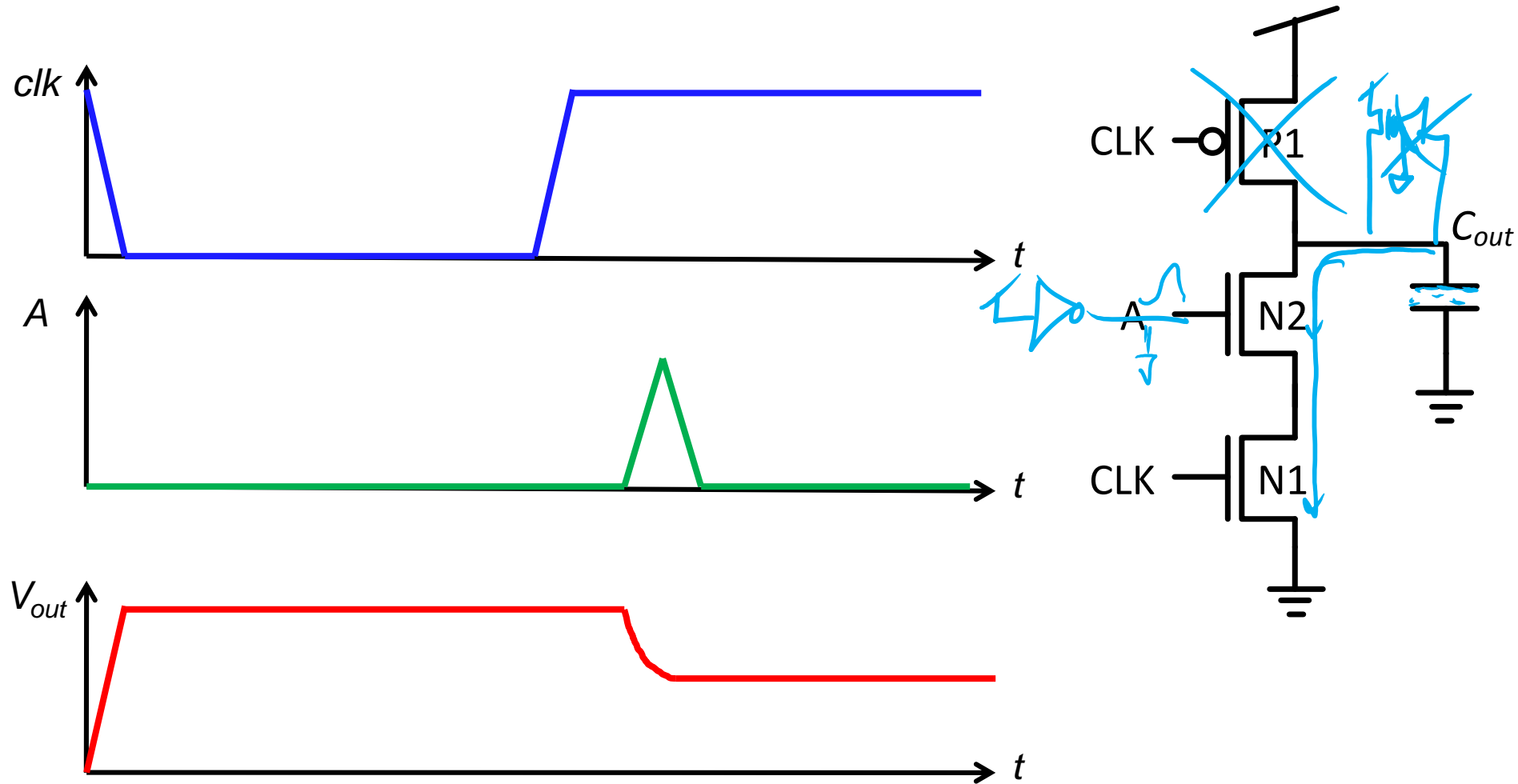
# Problem #1: Charge Loss

- ❑ *Dynamic Logic* only *pulls up the output* during the *Precharge Phase*.
- ❑ Therefore, any current that is *discharged* can only be *replenished* at the *next clock phase*.
- ❑ If a *low input* (that *cuts off the PDN*, leaving a *high output*) “*glitches*” from ‘0’ to ‘1’, a *path to ground* temporarily opens, *discharging* some of the output.
- ❑ In addition, *Static Leakage Current* through the *large nMOS* transistors *degrades the output level*.



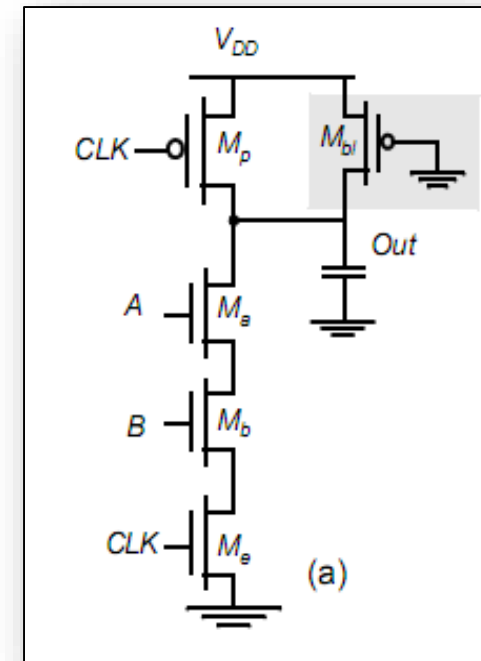


# Input Glitch Example



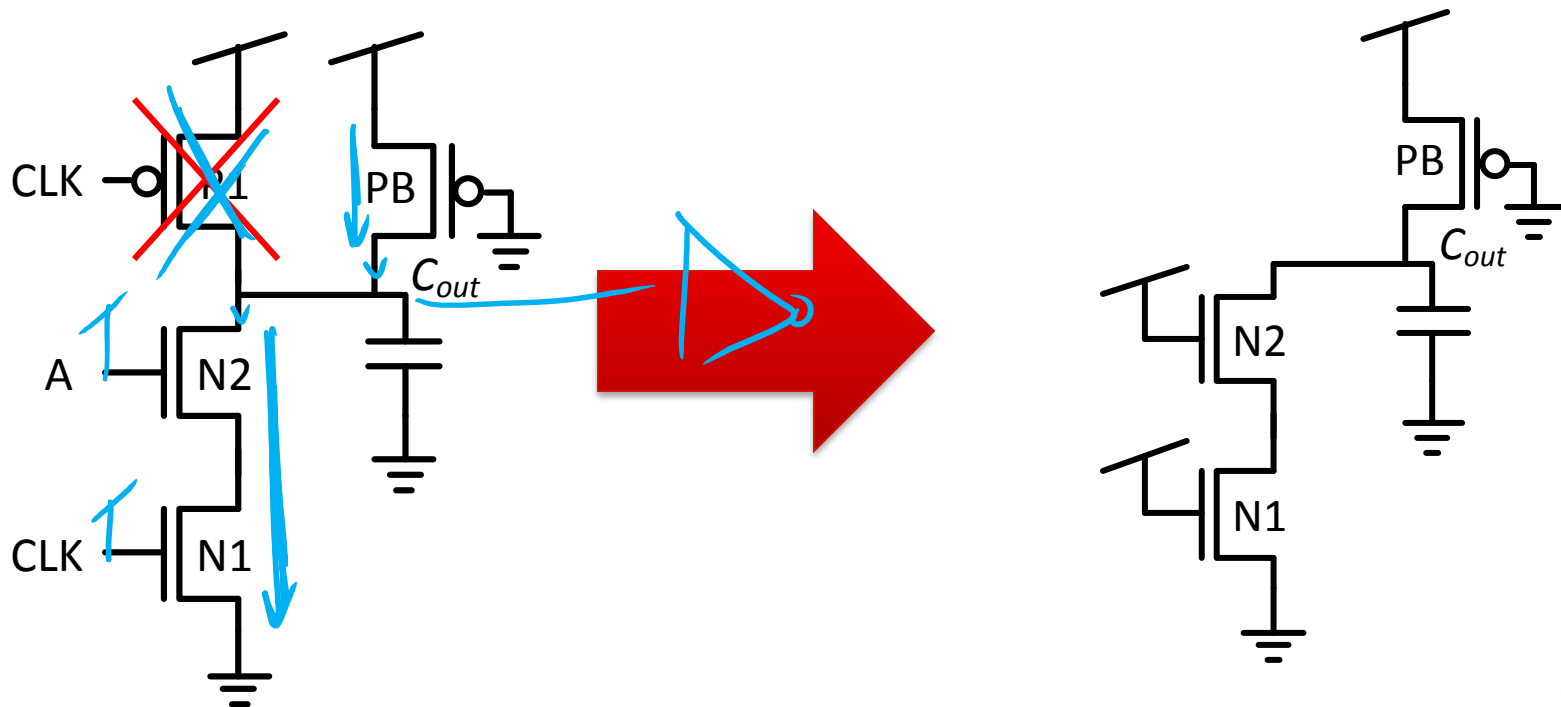
# Solution: Bleed Devices

- ❑ To fight the *Charge Loss* in an output node, a *Bleed Device* can be added:
- ❑ A small *Pseudo-nMOS* style *pMOS* is the basic implementation
  - » This causes  $V_{OLmin} > 0$ .
  - » Static Current Dissipation.



# Example – Bleed Device

- ❑ We have to carefully size the bleed device to trade off level compensation and static current.
- ❑ To find the static current, assume the gate is in *evaluation* with  $A=1$ .

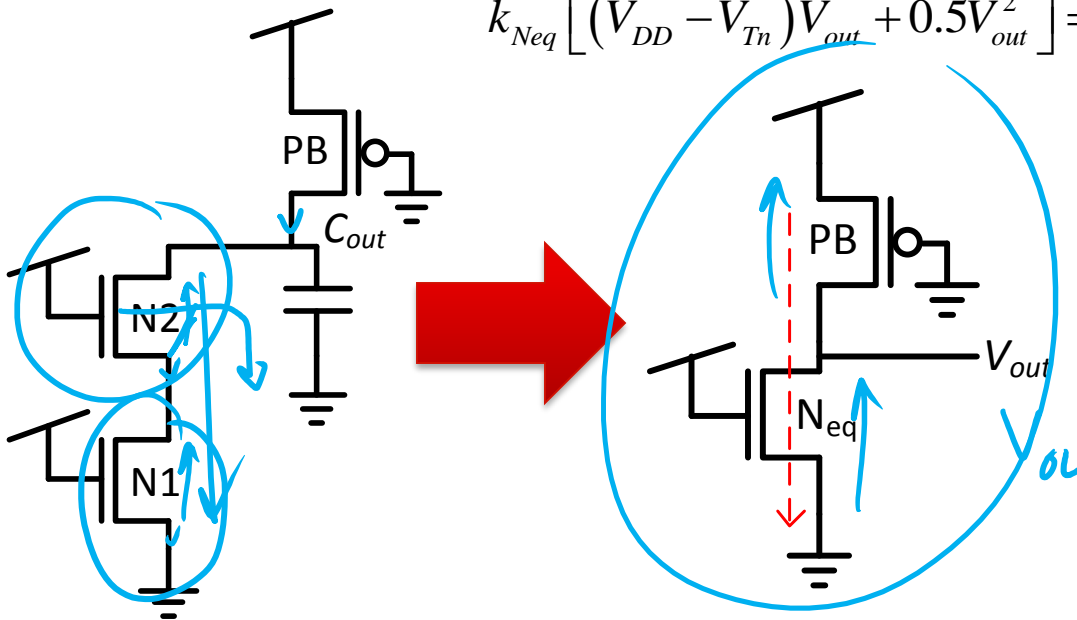


# Example – Bleed Device

- We now find the minimum output level.
- We can replace the two nMOS transistors with a single nMOS with  $L_{eq}=L_1+L_2$  (assuming they were sized with an equivalent  $W$ )

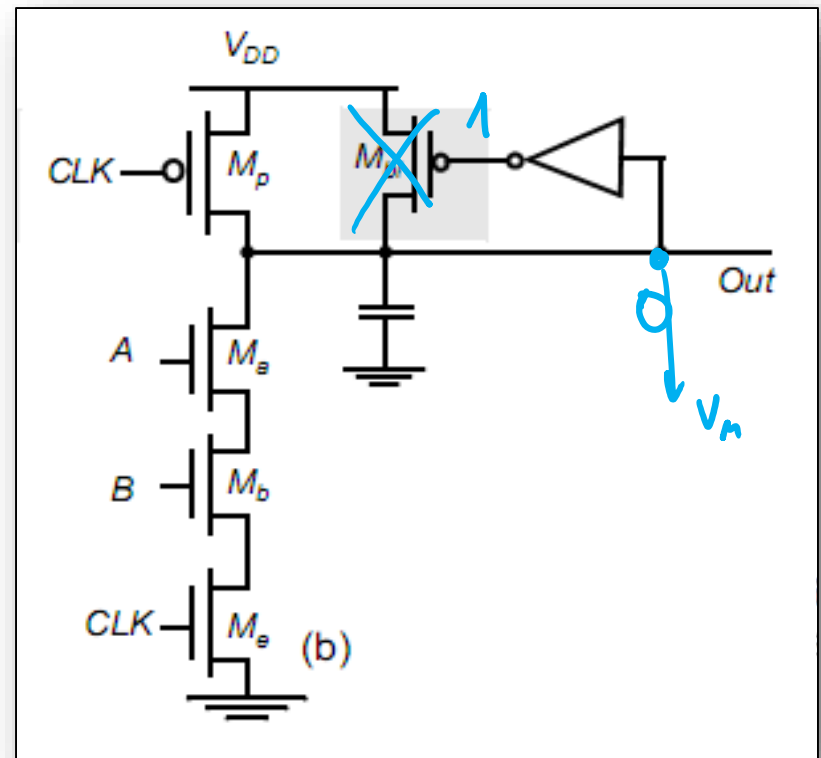
$$I_{Neq}(lin) = I_{PB}(vel.sat)$$

$$k_{Neq} \left[ (V_{DD} - V_{Tn}) V_{out} + 0.5 V_{out}^2 \right] = k_{PB} \left[ (V_{DD} - V_{Tp}) V_{Dsat,p} + 0.5 V_{Dsat,p}^2 \right]$$



# Feedback Bleed Device

- ❑ A better way to attach a bleed device is using feedback.
- ❑ In this way the bleed device is cut off when  $V_{out} = '0'$
- ❑ We get:
  - » Rail to Rail Swing
  - » No Static Current
  - » No glitching problem
- ❑ But:
  - » We still have to make sure the pull down network is strong enough to flip the inverter.
  - » We need an extra 3 transistors\*



*In a few minutes, we'll see that this is almost "free"*

# 10.3

**10.1 Dynamic CMOS**

**10.2 Charge Loss**

**10.3 Charge Sharing**

**10.4 Domino Logic**

**10.5 LE of Domino**

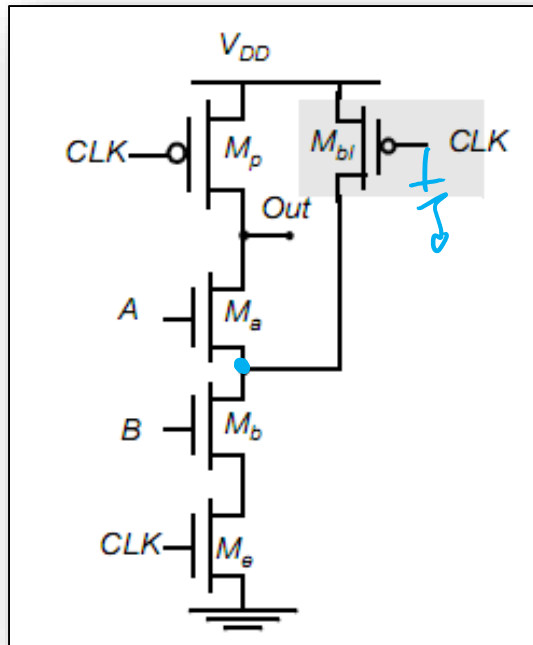


A secondary problem of Dynamic Gates is

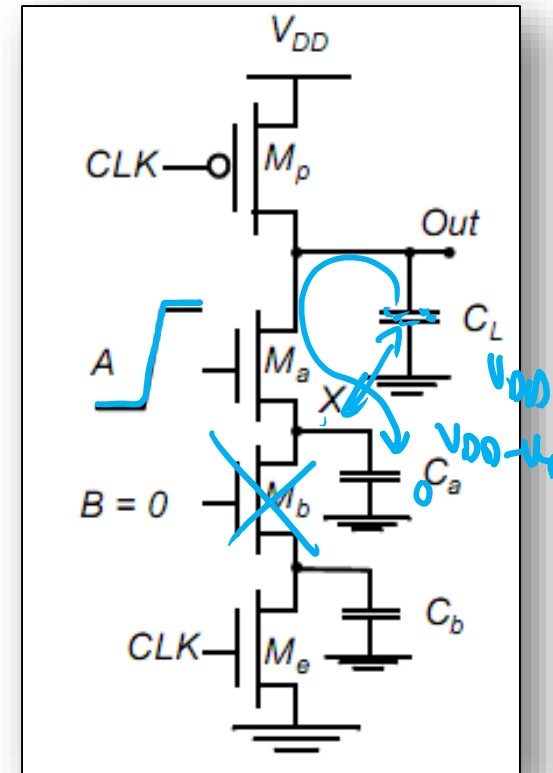
***CHARGE SHARING***

# Problem #2: Charge Sharing

- ❑ **Charge Sharing** occurs when the **PDN** is **closed**, but one or more **stacked transistors** next to the output are **open**.
  - » The charge is shared between the **output capacitance** and the **diffusion capacitance** of the **conducting transistor**.

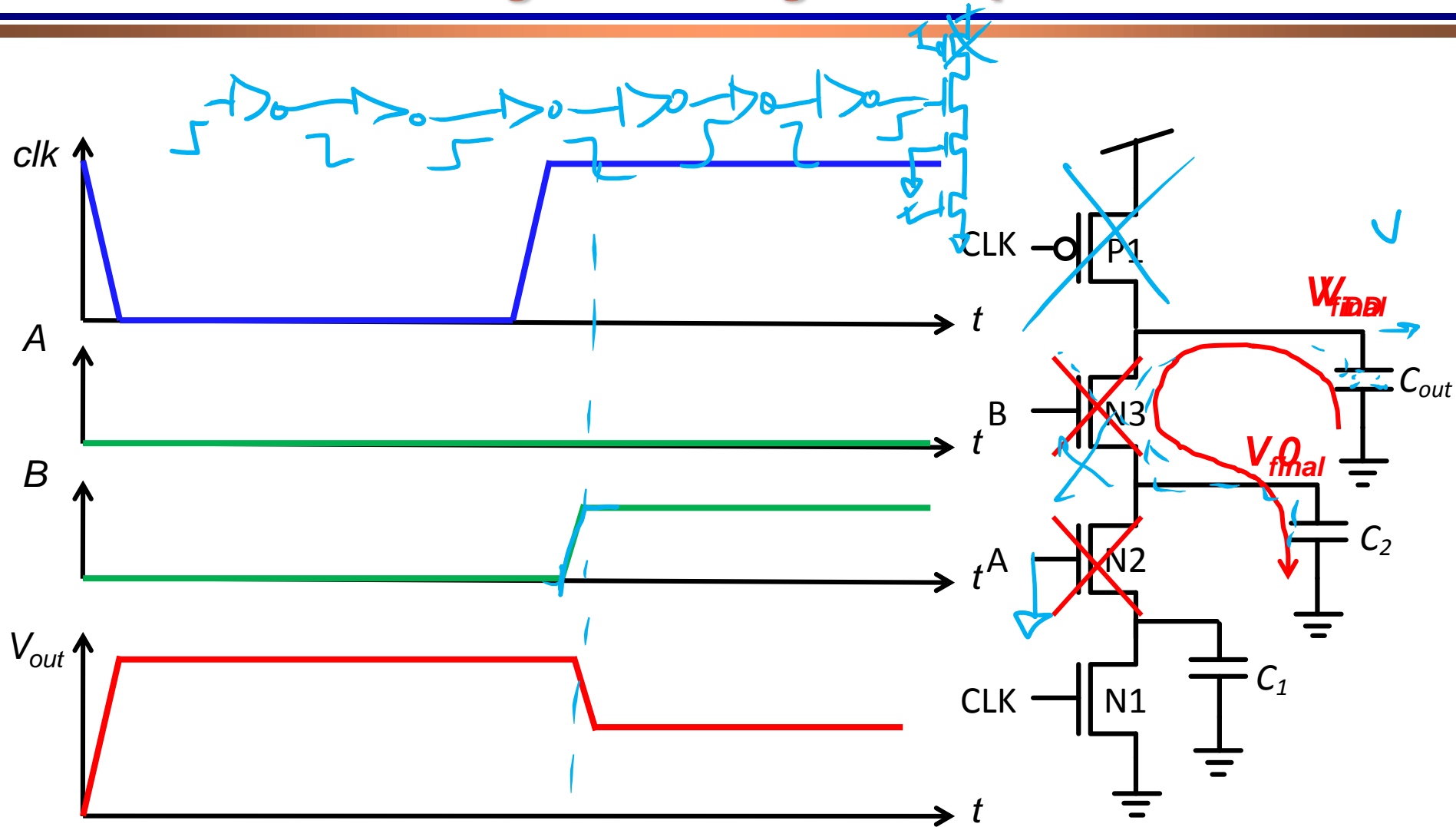


- ❑ One way to fix this is to **Precharge** these capacitances.





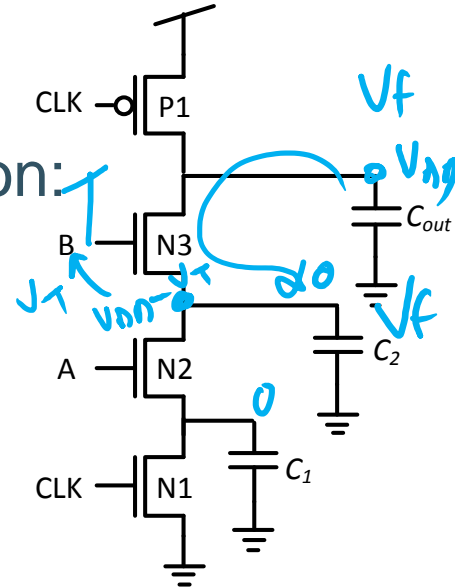
# Charge Sharing Example



# Charge Sharing Example

- How much charge is lost?
- We have to use Charge Conservation Equation:

$$Q_{initial} = Q_{final}$$



$$Q_{initial} = C_{out} \cdot V_{DD} \quad Q_{final} = C_{out} \cdot V_{final} + C_2 \cdot V_{final}$$

- Just don't forget to check if  $V_{final} > V_{DD} - V_{T...}$

$$C_{out} \cdot V_{final} + C_2 (V_{DD} - V_{th})$$

# 10.4

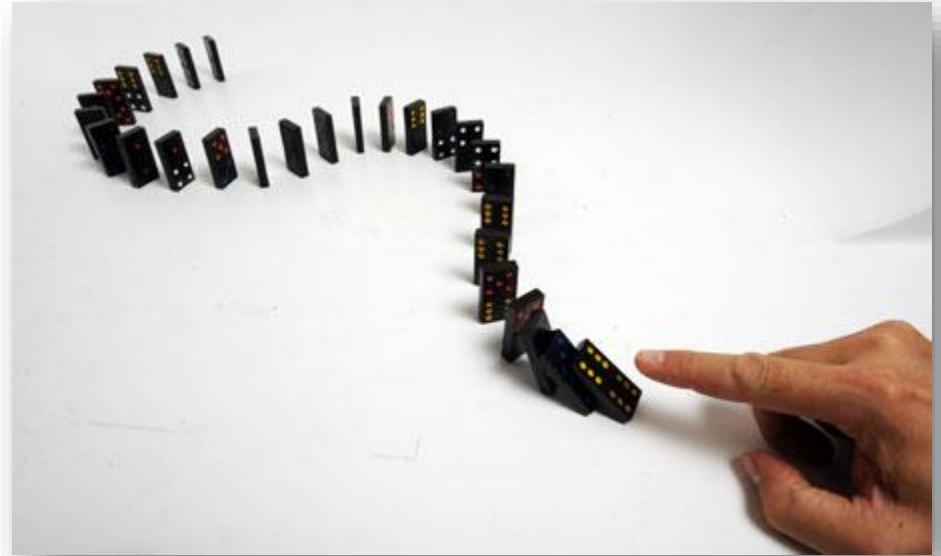
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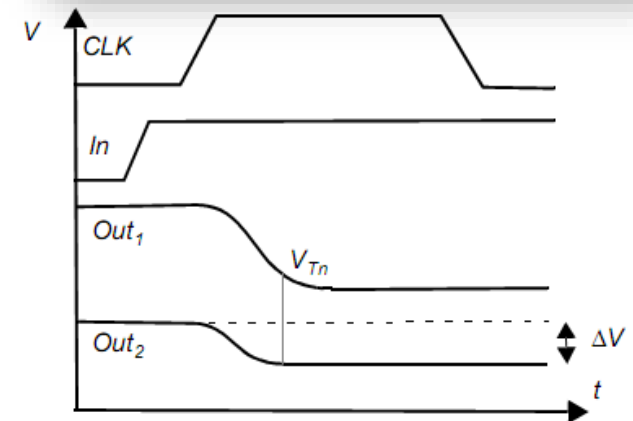
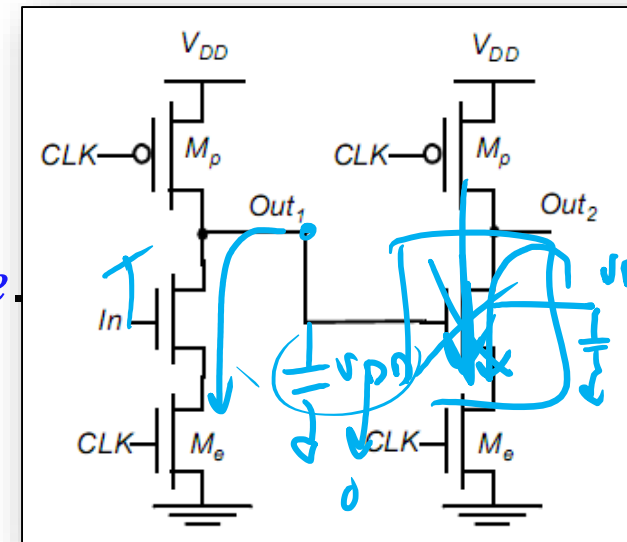
But the most interesting problem and solution comes with the need to hook up dynamic gates in a logic network, which brings us:

# *DOMINO LOGIC*

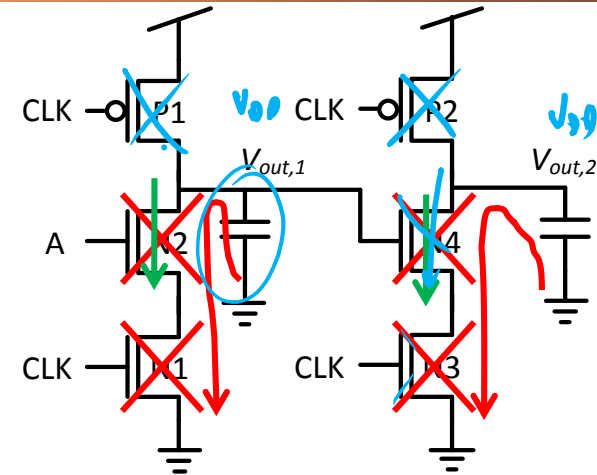
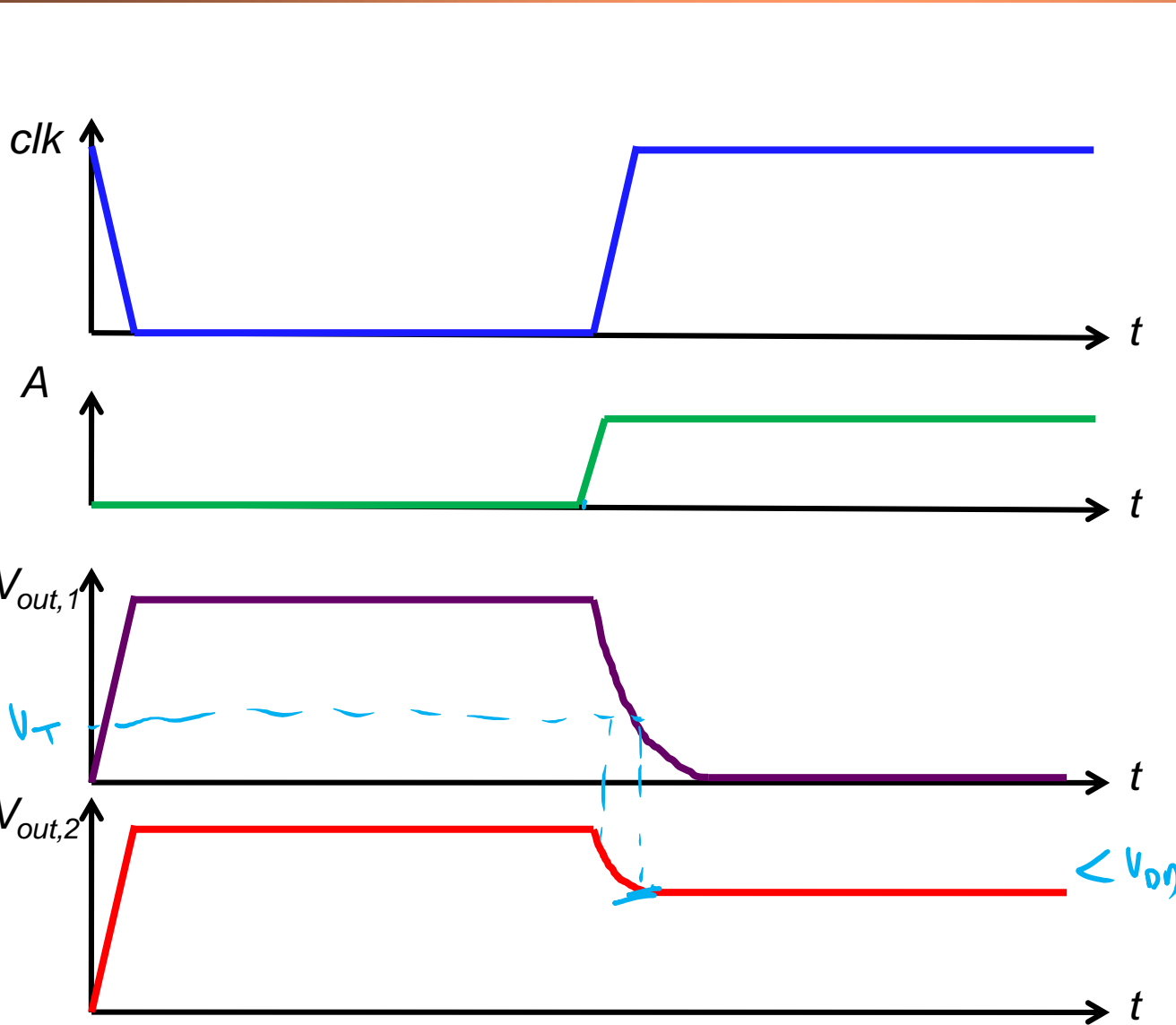
# Problem #3: Cascading Dynamic Gates

❑ The biggest drawback of **Dynamic Logic** is that **Dynamic Gates cannot be Cascaded**:

- » During **Precharge**, the output of the **Driving Gate** is charged to  $V_{DD}$ , turning on the **PDN** of the **Cascaded Gate**.
- » During the **Evaluation**, it takes time to discharge the output of the **Driving Gate** (considering it *should be Low*).
- » During this time, the **PDN** of the **Cascaded Gate** is **incorrectly conducting**, discharging its output.

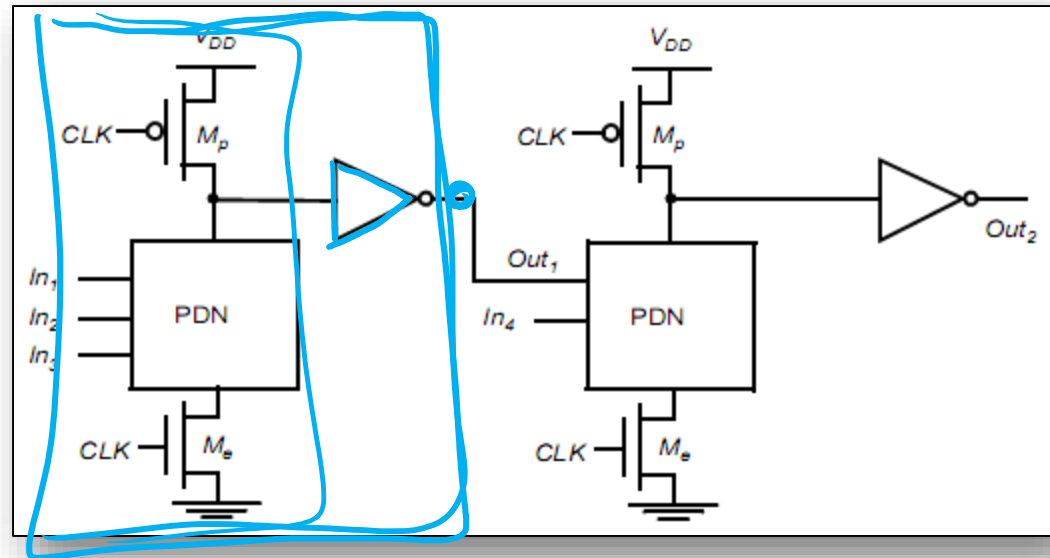


# Cascading Gates Example

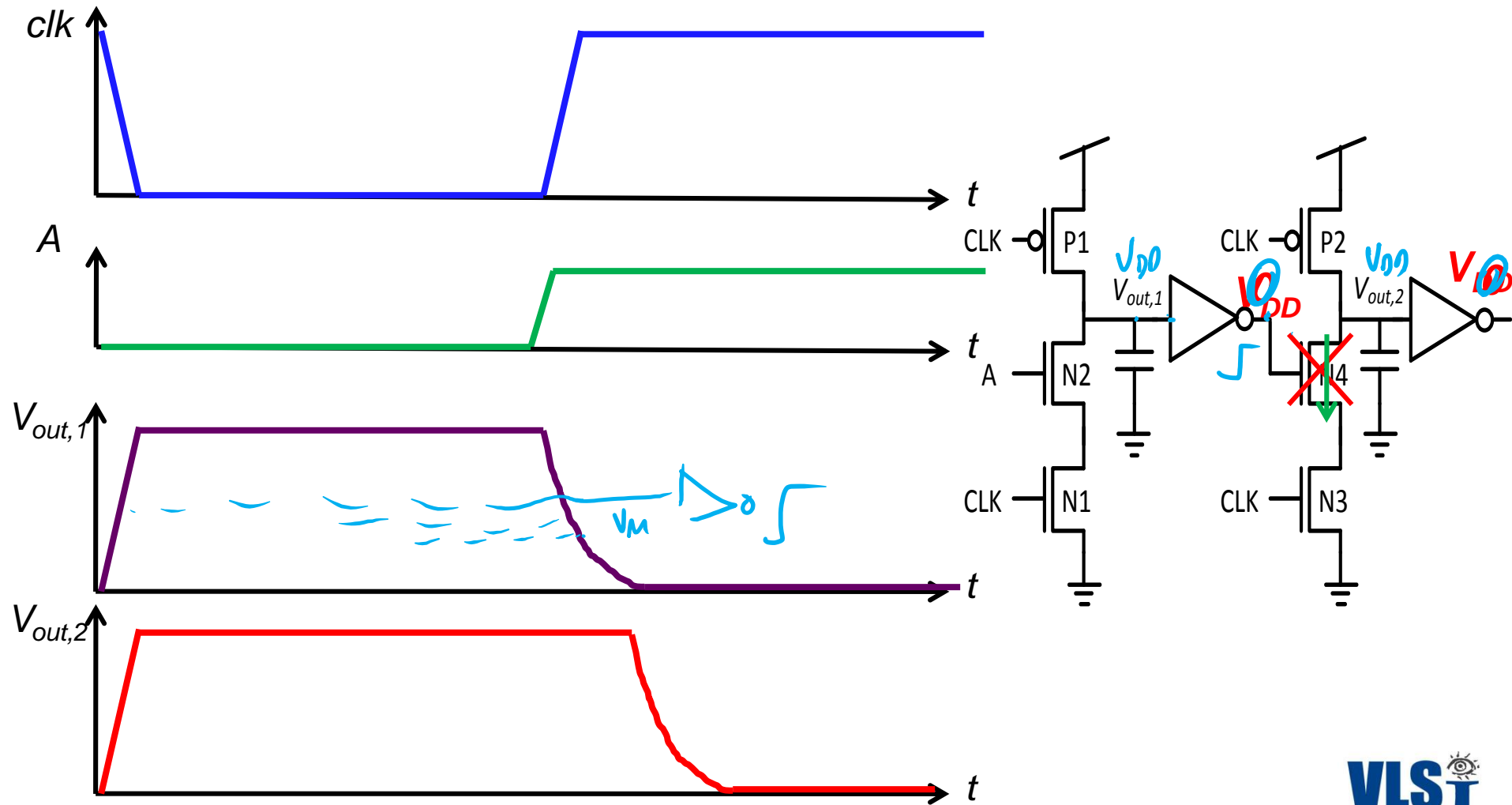


# Solution: Domino Logic

- ❑ One solution to the cascading problem is using ***“Domino Logic”***.
- ❑ Each ***Dynamic Gate*** is connected to an ***Inverter***, causing the ***input of the next gate*** to be ***Low after Precharge***.
- ❑ This ***solves the cascading problem*** and ***buffering gates*** provides several other ***advantages***.
- ❑ One ***major disadvantage*** occurs, though.
- ❑ **Can you guess what it is?** (Hint: ***Universality***)



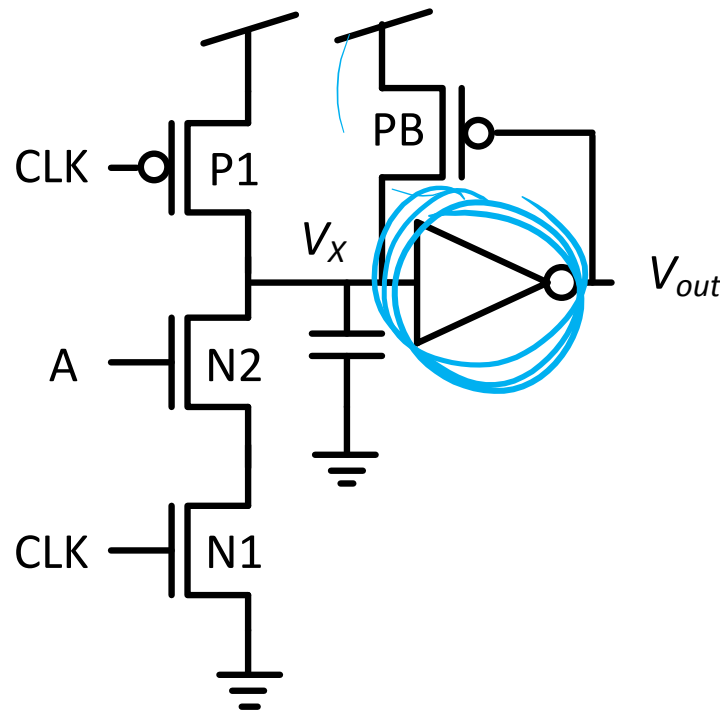
# Domino Logic Example





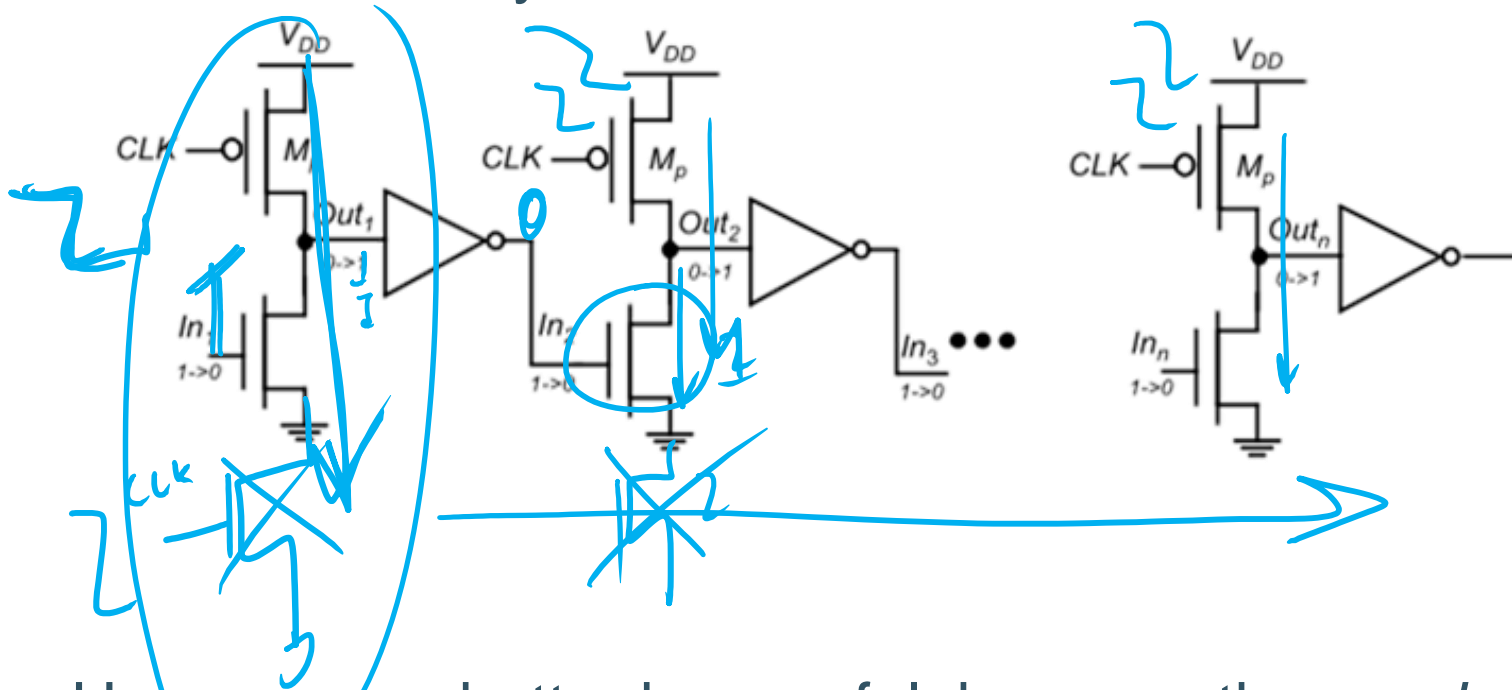
# Solving the Rest of Our Problems...

- Now we can freely add our feedback bleed transistor...



# Can we reduce the transistor count?

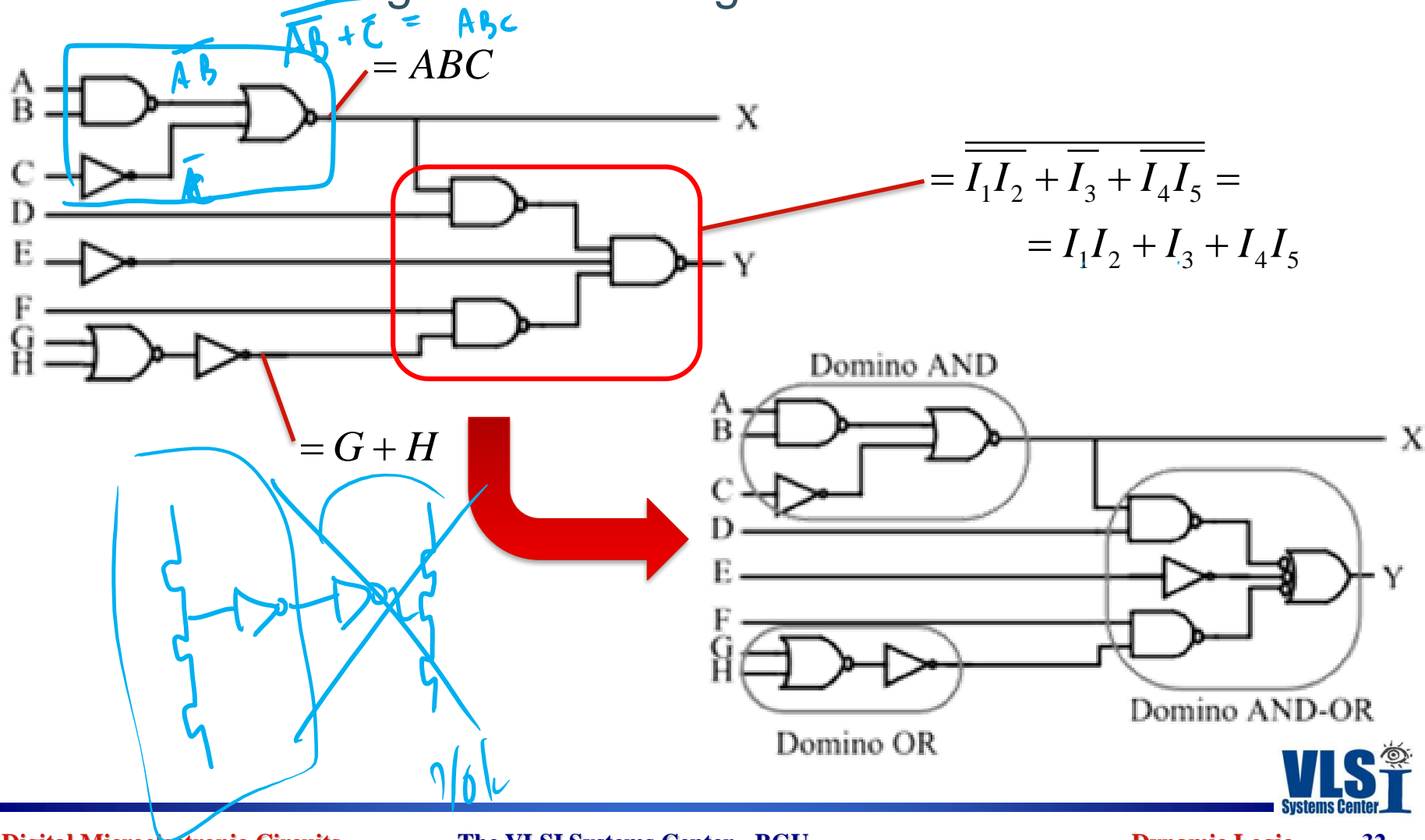
- Since the output of domino is always low during precharge, we don't actually need the evaluation transistor!



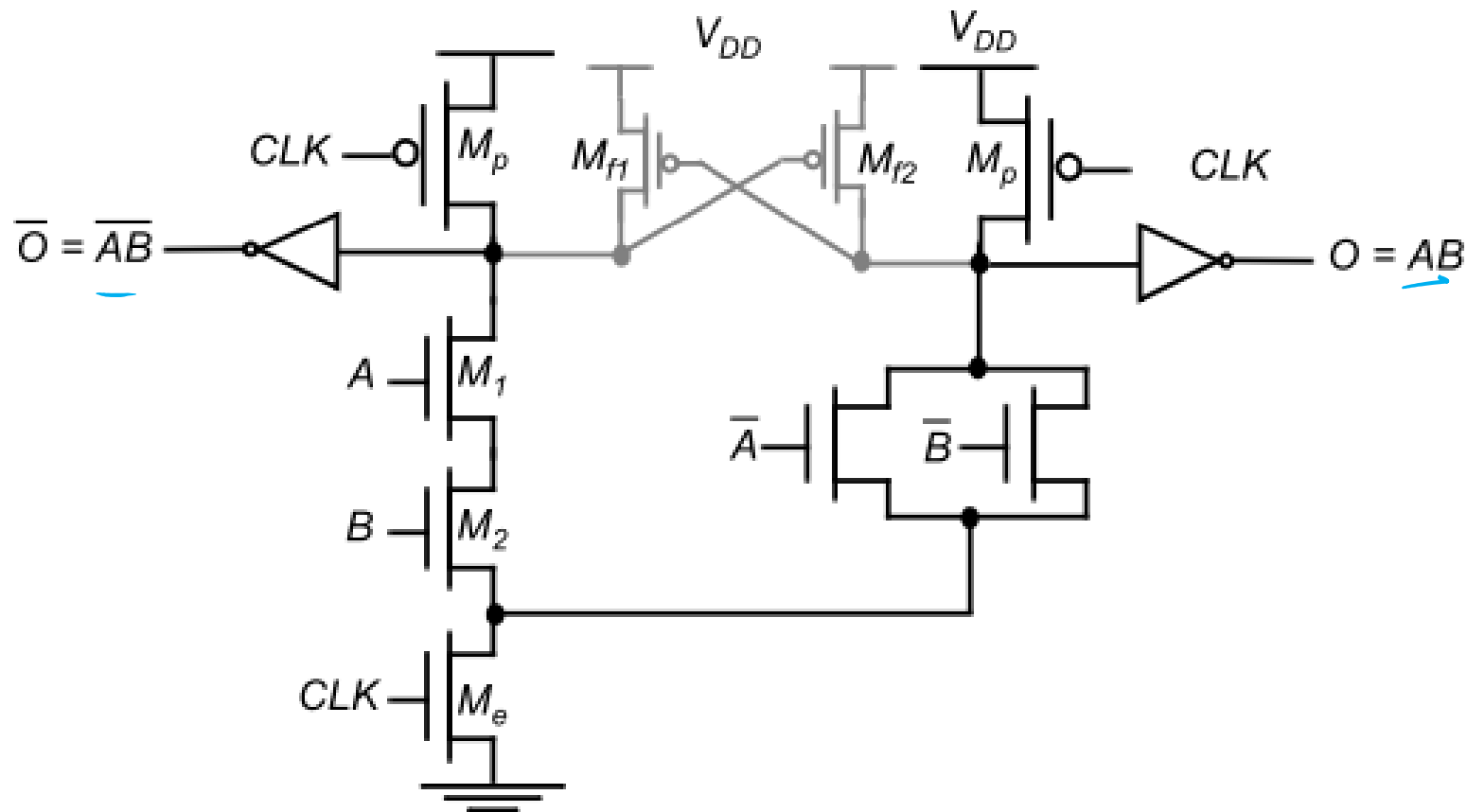
- However, we better be careful, because the *precharge* must now *propagate*, creating a constraint on the precharge time!

# What about universality?

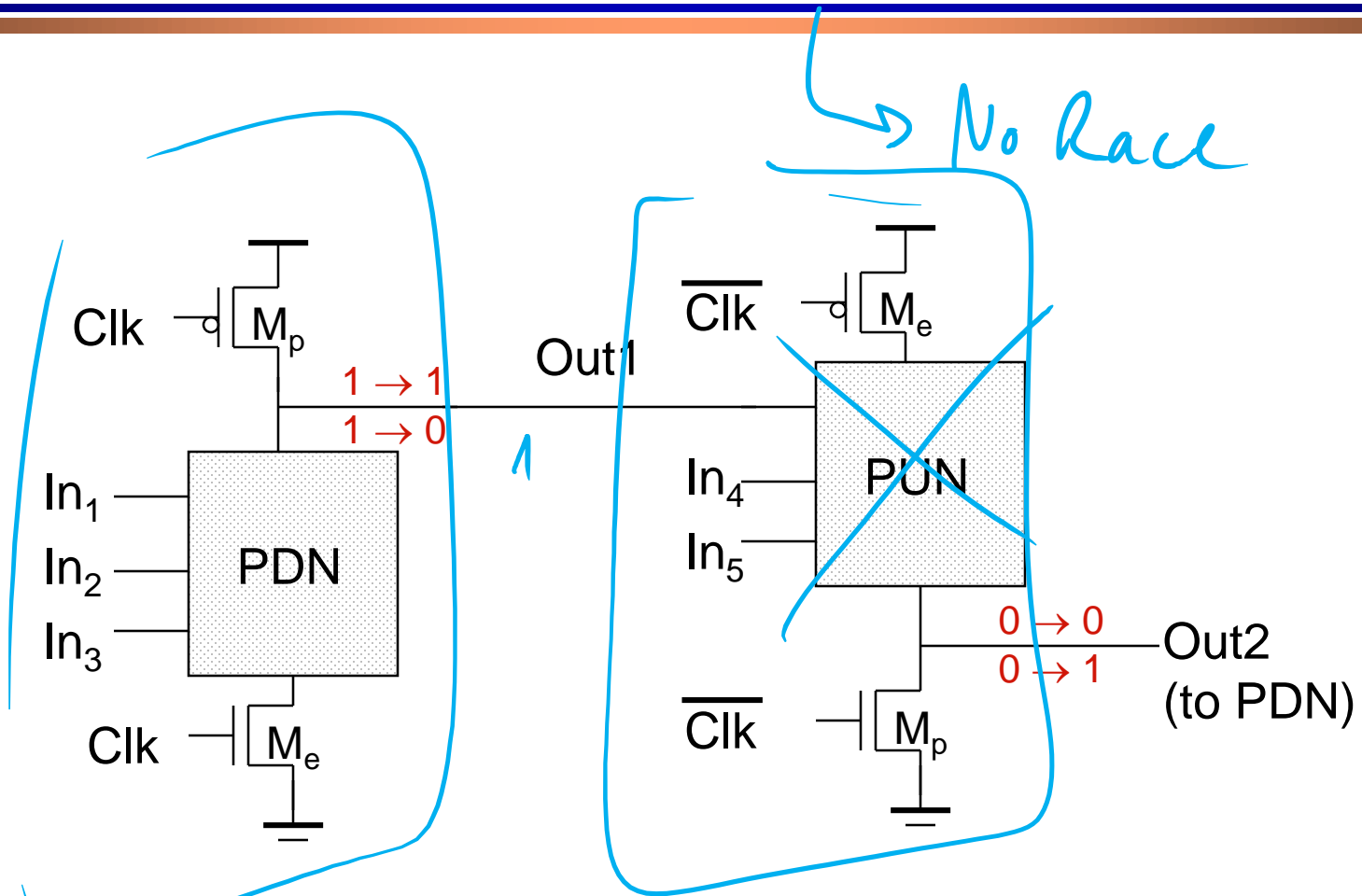
- Sometimes, logic restructuring works:



# Dual Rail Domino



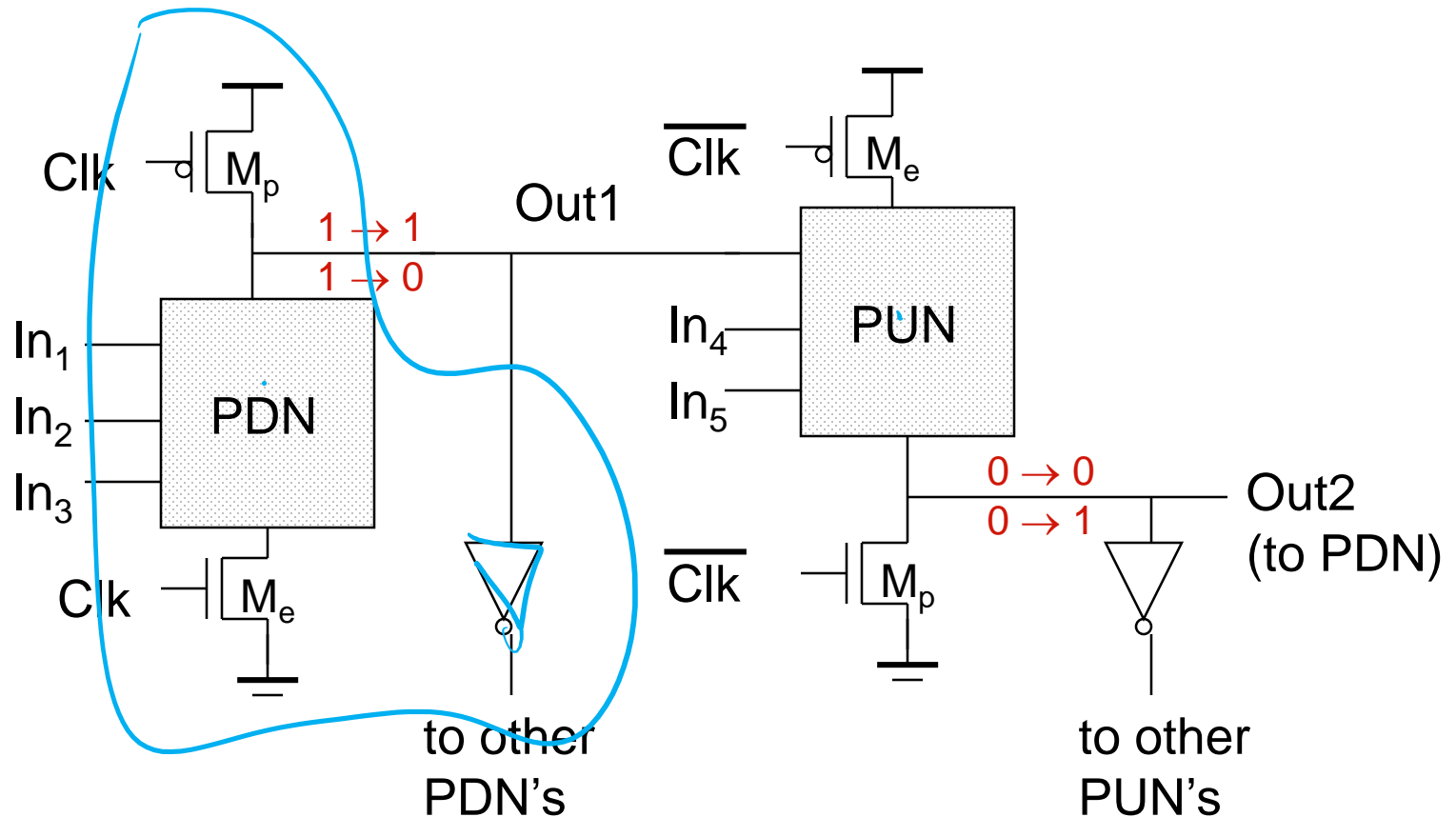
# np-CMOS (NORA)



Only  $0 \rightarrow 1$  transitions allowed at inputs of PDN

Only  $1 \rightarrow 0$  transitions allowed at inputs of PUN

# np-CMOS



# 10.5

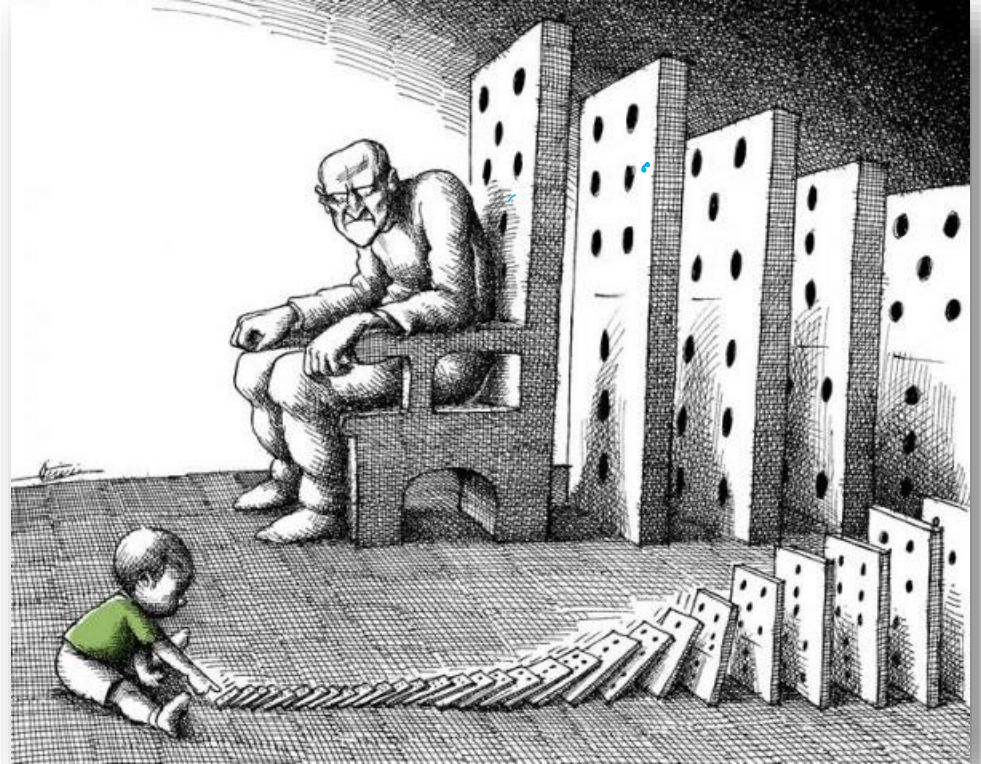
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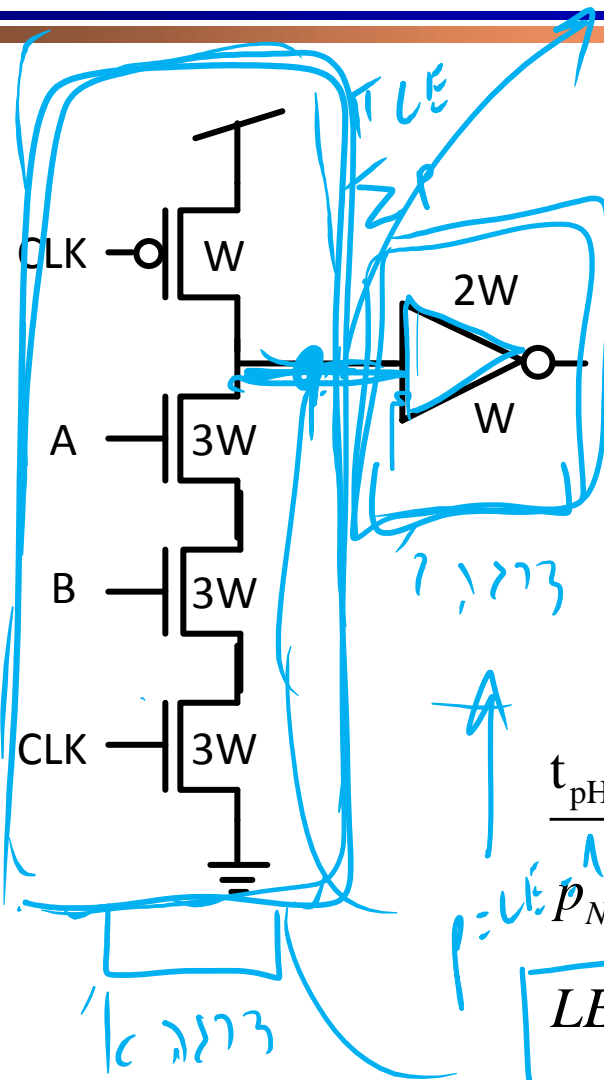


Finally, let's see how domino gates behave in a logic network:

## ***LOGICAL EFFORT OF DOMINO LOGIC***



# Domino Logic Logical Effort



$t_{pHL}$  (NAND):

$$R_{eq} = R_{min}$$

$$C_g(A, B) = 3C_{gmin}$$

$$C_d = 4C_{dmin}$$

$$p_{NAND} = \frac{4}{3}$$

$$LE_{NAND} = 1$$

$$\Pi LE_{NAND} = 1 \cdot 1 = 1$$

$$\Sigma p_{NAND} = \frac{4}{3} + 1 = \frac{7}{3}$$

$t_{pHL}$  (NOR):

$$p_{NOR} = \frac{5}{3}$$

$$LE_{NOR} = \frac{2}{3}$$

$$\Sigma p_{NOR} = \frac{5}{3} + 1 = \frac{8}{3}$$

$$\Pi LE_{NOR} = \frac{2}{3} \cdot 1 = \frac{2}{3}$$

# Domino Logic Logical Effort

- We can improve this by using a “skewed inverter”
- For a standard Domino NAND, we got:

$$p_{NAND} = \frac{4}{3} \quad LE_{NAND} = 1 \quad \Pi LE_{NAND} = 1 \quad \Sigma p_{NAND} = \frac{7}{3}$$

- But if we enlarge the pMOS of the inverter, we get:

$t_{pLH}$  :

$$p_{INV^*} = LE_{INV^*} = \frac{1}{2} \cdot \frac{5}{3} = \frac{5}{6}$$

$$\Pi LE_{NAND^*} = 1 \cdot \frac{5}{6} = \frac{5}{6} \quad \Sigma p_{NAND} = \frac{4}{3} + \frac{5}{6} = \frac{13}{6}$$

- The “Average” LE (~stage effort) is:

$$\sqrt{\Pi LE_{NAND^*}} = \sqrt{\frac{5}{6}} = 0.91$$

